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Digital Signal Processing 2 **Les 5: Detectieproblemen**

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Digital Signal Processing 2: Vakinhoud

- Les 1: Eindige woordlengte
- Les 2: Lineaire predictie
- Les 3: Optimale filtering
- Les 4: Adaptieve filtering
- Les 5: Detectieproblemen
- Les 6: Spectrale signaalanalyse
- Les 7: Schattingsproblemen 1
- Les 8: Schattingsproblemen 2
- Les 9: Sigma-Deltamodulatie
- Les 10: Transformatiecodering

• **Signal detection**

introduction, binary hypothesis testing, …

- **Example: detection of sinusoid in noise** energy detection, periodogram-based detection, …
- **Detection performance analysis** confusion matrix, receiver operating characteristic (ROC), …

- **Signal detection**
- **Example: detection of sinusoid in noise**
	- Research paper:

H. C. So *et al.*, "Comparison of various periodograms for sinusoid detection and frequency estimation," *IEEE Trans. Aerospace Electron. Syst.*, vol. 35, no. 3, July 1999, pp. 945-952.

(Section I–II)

Matlab code:

DSP2 sinusoid detection.m (available on Toledo)

• **Detection performance analysis**

Research paper:

T. Fawcett, "An introduction to ROC analysis," *Patt. Recognition Lett.*, vol. 27, 2006, pp. 861-874.

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(Section 1–3)

- **Signal detection** introduction, binary hypothesis testing, …
- **Example: detection of sinusoid in noise** energy detection, periodogram-based detection, …
- **Detection performance analysis** confusion matrix, receiver operating characteristic (ROC), …

Signal detection

- Introduction
- Binary hypothesis testing

Introduction

- **Signal detection**
	- problem of determining whether or not signal is active
	- trivial problem in noiseless case (amplitude $\neq 0$?)
	- challenging problem in noisy case (e.g. sinusoid in noise)

Detection ≠ Estimation !!!

- estimation: real-valued result
- detection: binary result

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Signal detection

- Introduction
- Binary hypothesis testing

Binary hypothesis testing (1)

- **Two hypotheses**
	- $-$ null hypothesis \mathcal{H}_0 : signal is not active
	- $-$ alternative hypothesis \mathcal{H}_1 : signal is active

• **Two detection outcomes**

- null hypothesis is rejected (signal is detected)
- null hypothesis is not rejected (no signal is detected)

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Binary hypothesis testing (2)

- **Observed signal**
	- observation: data vector of length *N*

$$
\mathbf{y} = [y(0) \quad y(1) \quad \dots \quad y(N-1)]^T
$$

- **Signal features**
	- signal properties that are most characteristic of signal (and can hence be used to detect the signal)

$$
\mathbf{f} = \begin{bmatrix} f_0 & f_1 & \dots & f_{P-1} \end{bmatrix}^T
$$

- **Detection function**
	- function that "summarizes" feature values to single value

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$$
\delta(\mathbf{f}) \in \mathbb{R}
$$

Binary hypothesis testing (3)

- **Binary hypothesis test**
	- single-feature test: comparison of detection function to threshold

 $\delta(\mathbf{f}) \geq T \Rightarrow$ reject \mathcal{H}_0

- multiple-feature test: logical conjunction of single-feature tests, using multiple feature vectors, detection functions and thresholds

Binary hypothesis testing (3)

• **Discriminative power**

- how easy is it to discriminate \mathcal{H}_1 from \mathcal{H}_0 based on detection function value $\,\delta({\bf f})\,?\,$
- denote detection function value
	- by $\delta(\mathbf{f}, \mathcal{H}_1)$ for observation with active signal
	- by $\delta(\mathbf{f},\mathcal{H}_0)$ for observation without active signal
- optimal threshold value *T* should be in between both detection function values:

 $\delta(\mathbf{f}, \mathcal{H}_1) \geq T > \delta(\mathbf{f}, \mathcal{H}_0)$

- discriminative power of detection algorithm
	- is determined by choice of signal features and detection function
	- can be quantified by means of ratio

$$
\frac{\delta(\mathbf{f}, \mathcal{H}_1)}{\delta(\mathbf{f}, \mathcal{H}_0)}
$$

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- **Signal detection** introduction, binary hypothesis testing, …
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Example: detection of sinusoid in noise (1)

• **Problem statement**

- observation consisting of two fragments (active/inactive):

$$
\begin{cases} y(n) = \sin(\omega n) + e(n), & n = 0, ..., N/2 - 1 \\ y(n) = e(n), & n = N/2, ..., N - 1 \end{cases}
$$

Gaussian white noise

$$
e(n) \sim \mathcal{N}(0, \sigma_e^2)
$$

- $-$ SNR = 0 dB
- $N = 1000$

$$
-\omega = 0.05 \text{ rad/s}
$$

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Example: detection of sinusoid in noise (2)

• **Method 1: energy detection**

- features: squared signal values

$$
\mathbf{f} = \begin{bmatrix} y^2(0) & y^2(1) & \dots & y^2(N-1) \end{bmatrix}^T
$$

- detection function: mean of feature values

$$
\delta(\mathbf{f}) = \frac{1}{N} \sum_{p=0}^{N-1} f_p = \frac{1}{N} \sum_{n=0}^{N-1} y^2(n) = \frac{1}{N} \mathbf{y}^T \mathbf{y}
$$

 $-$ hypothesis test: $\delta(\mathbf{f}) \geq T \Rightarrow$ reject \mathcal{H}_0 (a, a) throshold $T = no^{\prime}$ power)

(e.g. inresnola
$$
I =
$$
 noise power)
\n
$$
\xrightarrow{\qquad \qquad} \qquad I
$$
\n
$$
\xrightarrow{\qquad \qquad} \delta(f) \geq T
$$
\n
$$
\xrightarrow{\text{reject'}} \mathcal{H}_0
$$
\n
$$
\xrightarrow{\qquad \qquad} \text{accept}} \mathcal{H}_0
$$

Example: detection of sinusoid in noise (3)

• **Method 1: energy detection**

Example: detection of sinusoid in noise (4)

- **Method 2: periodogram-based energy detection**
	- features: squared DFT magnitude values (= periodogram)

$$
\mathbf{f} = [|Y(0)|^2 \quad |Y(1)|^2 \quad \dots \quad |Y(N-1)|^2]^T
$$

with $Y = DFT(y)$

- detection function: maximum of feature values (why?)

$$
\delta(\mathbf{f}) = \max(\mathbf{f}) = \max_{k} |Y(k)|^2
$$

 $-$ hypothesis test: $\delta(\mathbf{f}) \geq T \Rightarrow$ reject \mathcal{H}_0 (e.g. threshold $T = noise power$) *T*

$$
\xrightarrow{\mathbf{DFT}(\cdot)^2} \mathbf{f} \longrightarrow \text{max} \qquad \frac{\delta(\mathbf{f})}{\delta(\mathbf{f}) \geq T} \longrightarrow \text{right} \qquad \mathcal{H}_0
$$

Example: detection of sinusoid in noise (5)

• **Method 2: periodogram-based energy detection**

Example: detection of sinusoid in noise (6)

- **Method 3: periodogram-based energy detection with known sinusoid frequency**
	- features: squared DFT magnitude values (= periodogram)

$$
\mathbf{f} = [|Y(0)|^2 \quad |Y(1)|^2 \quad \dots \quad |Y(N-1)|^2]^T
$$

with $Y = DFT(y)$

 $-$ detection function: feature value at DFT bin $k =$

$$
\left\lfloor \frac{\omega(N/2)}{2\pi} \right\rceil
$$

$$
\delta(\mathbf{f}) = |Y(k)|^2
$$

 $-$ hypothesis test: $\delta(\mathbf{f}) \geq T \Rightarrow$ reject \mathcal{H}_0 *T*

$$
11 \text{ y} \text{ p} \text{ of } 7 \text{ s} \text{ is } 10 \text{ m} \text{ s} \text{ is } 10 \text{ m}
$$
\n
$$
(e.g., threshold \text{ } 7 = \text{noise power})
$$

$$
\xrightarrow{\mathbf{y}} |\text{DFT}(\cdot)|^2 \qquad \qquad \mathbf{f} \qquad \qquad k = \left\lfloor \frac{\omega(N/2)}{2\pi} \right\rfloor \qquad \qquad \delta(\mathbf{f}) \geq T \qquad \qquad \text{respectly} \qquad \mathcal{H}_0
$$

Example: detection of sinusoid in noise (7)

• **Method 3: periodogram-based energy detection with known sinusoid frequency** - detection function

• **Signal detection**

introduction, binary hypothesis testing, …

- **Example: detection of sinusoid in noise** energy detection, periodogram-based detection, …
- **Detection performance analysis** confusion matrix, receiver operating characteristic (ROC), …

Detection performance analysis

- Performance measures
- Confusion matrix
- Receiver operating characteristic

Performance measures (1)

- **Data realizations:**
	- suppose we have *R* realizations of the observation vector **y**

$$
\mathbf{y}^{(1)},\ldots,\mathbf{y}^{(R)}
$$

- each realization either corresponds to:
	- active signal (positive realization), or
	- no active signal (negative realization)
- number of positive and negative realizations:

 $R_P + R_N = R$

- performance analysis should be based on "balanced" set of data realizations, i.e. $R_P \approx R_N$

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Performance measures (2)

• **Detection outcomes**

- $-$ true positive: \mathcal{H}_0 rejected for positive realization
- $-$ false positive: \mathcal{H}_0 rejected for negative realization
- true negative: \mathcal{H}_0 not rejected for negative realization H_0
- false negative: \mathcal{H}_0 not rejected for positive realization H_0

• **Counting detection outcomes**

- R_{TP} : number of true positives
- R_{FP} : number of false positives
- R_{TN} : number of true negatives
- R_{FN} : number of false negatives

Performance measures (3)

• **Performance measures:**

 $-$ probability of detection $=$ true positives rate $=$ recall

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$$
P_D=P(\mathcal{H}_1;\mathcal{H}_1)=\frac{R_{TF}}{R_P}
$$

- probability of false alarm = false positives rate

$$
P_{FA} = P(\mathcal{H}_1; \mathcal{H}_0) = \frac{R_{FP}}{R_N}
$$

- precision =
$$
\frac{R_{TP}}{R_{TP} + R_{FP}}
$$

- accuracy =
$$
\frac{R_{TP} + R_{TN}}{R}
$$

- F-measure =
$$
\frac{2}{1/\text{precision} + 1/\text{recall}}
$$

Detection performance analysis

- Performance measures
- Confusion matrix
- Receiver operating characteristic

Confusion matrix

• **Confusion matrix**

- 2 x 2 representation of counted detection outcomes

Fig. 1. Confusion matrix and common performance metrics calculated from it.

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Detection performance analysis

- Performance measures
- Confusion matrix
- Receiver operating characteristic

Receiver operating characteristic (1)

- **Receiver operating characteristic (ROC)**
	- $-$ 2-dimensional representation of (R_{FP}, R_{TP}) -curve obtained for different threshold values in range $T\in [0,\infty]$

Receiver operating characteristic (2)

- **ROC interpretation:**
	- $-$ ROC curve = on or below diagonal line from $(0,0)$ to $(1,1)$: useless detector (not better than random decision)
	- $-$ ROC curve = line segments from $(0,0)$ and $(1,1)$ to $(0,1)$: ideal detector
	- area under ROC curve = number to compare different ROC curves

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