

Summer Course

**Linear System Theory
Control
&
Matrix Computations**

Monopoli

September 8–12, 2008

Lecture 14: Dissipative systems

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Part I: General dissipative systems

Outline

The dissipation inequality

The dissipation equality

Dissipation inequality

Physical examples:

- **Resistive electrical circuits;**
- **Mechanical systems with friction;**
- ...

Dissipation inequality

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Energy supplied to system \rightsquigarrow **supply rate variable** F_Σ

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- Electrical circuits: $V^\top I$ with V (I) vector of voltages (currents)

Dissipation inequality

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- Mechanical systems with friction;
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- Electrical circuits: $V^\top I$ with V (I) vector of voltages (currents)
- Mechanical systems: $F^\top \frac{d}{dt}x$ with F (x) vector of forces (displacements)

Dissipation inequality

Energy supplied to system \rightsquigarrow **supply rate variable** F_Σ

Energy stored in system \rightsquigarrow **storage variable** F_S

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- Electrical circuits: $\frac{1}{2}C \cdot V^2$ for capacitor, $\frac{1}{2}L \cdot I^2$ for inductor

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- **Electrical circuits:** $\frac{1}{2}C \cdot V^2$ for capacitor, $\frac{1}{2}L \cdot I^2$ for inductor
- **Mechanical systems:** $\frac{1}{2}K \cdot x^2$ for spring

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**In a dissipative system,
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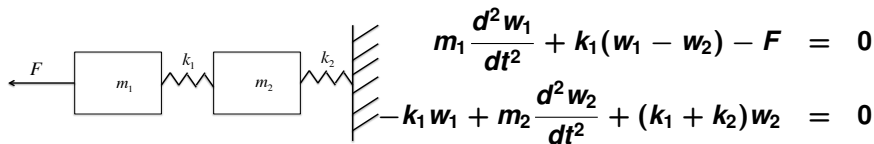
$$F_\Delta := F_\Sigma - \frac{d}{dt}F_S \quad \text{dissipation rate (nonnegative)}$$

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Dissipation equality

Lossless systems: $F_\Sigma = \frac{d}{dt}F_S$

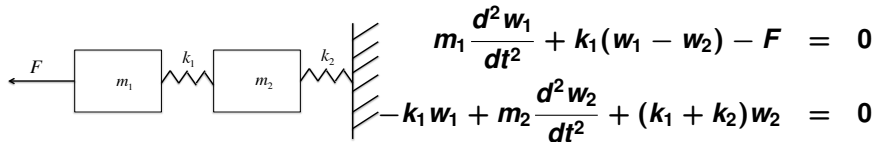
Example : a mechanical system



$$m_1 \frac{d^2 w_1}{dt^2} + k_1 (w_1 - w_2) - F = 0$$

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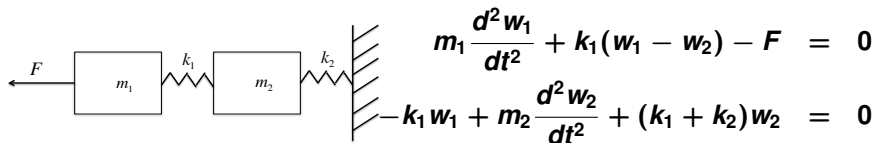


From physical considerations:

supply (power) $F \cdot \frac{dw_1}{dt}$

storage (total energy) $\frac{1}{2} m_1 \left(\frac{dw_1}{dt} \right)^2 + \frac{1}{2} m_2 \left(\frac{dw_2}{dt} \right)^2$
 $+ \frac{1}{2} k_1 (w_1 - w_2)^2 + \frac{1}{2} k_2 w_2^2$

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Easy to see that

$$\frac{d}{dt} \left(F \frac{dw_1}{dt} \right) = \frac{1}{2} m_1 \left(\frac{dw_1}{dt} \right)^2 + \frac{1}{2} m_2 \left(\frac{dw_2}{dt} \right)^2 + \frac{1}{2} k_1 (w_1 - w_2)^2 + \frac{1}{2} k_2 w_2^2$$

Remarks

- **Supply, storage, dissipation for physical system example are functions of the system variables and their (first) derivatives.**

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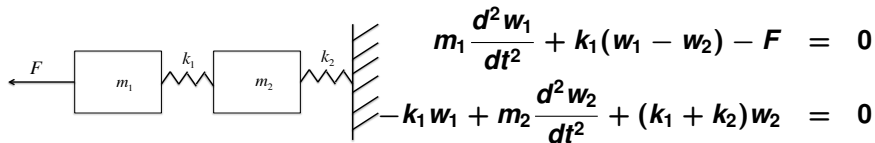
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- **Supply, storage, dissipation for physical system example are functions of the system variables and their (first) derivatives.**
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- **What if linear time-invariant finite-dimensional systems, with quadratic supply rates?**

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- **Supply, storage, dissipation for physical system example are functions of the system variables and their (first) derivatives.**
- **Existential definition: “*if \exists storage function...*”**
- **¿Can we decide whether a system is dissipative by examining the supply rate?**
- **What if linear time-invariant finite-dimensional systems, with quadratic supply rates?**
- **¡We need theoretical and algebraic tools!**

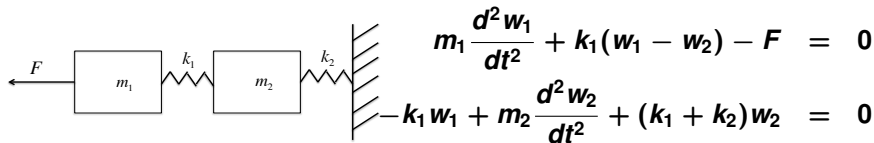
Mechanical system example revisited



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Mechanical system example revisited

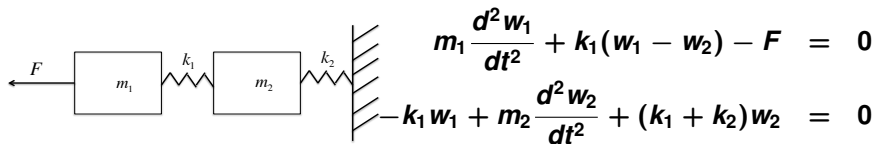


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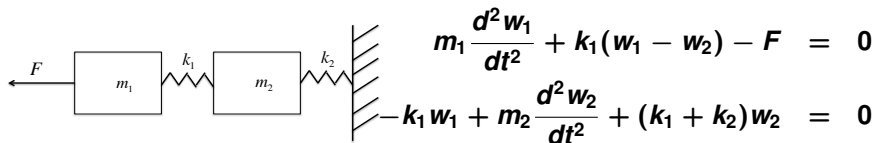
Only dynamics of w_1 of interest \implies eliminate w_2

Mechanical system example revisited



$$m_1 m_2 \frac{d^4}{dt^4} w_1 + (k_1 m_1 + k_2 m_1 + k_1 m_2) \frac{d^2}{dt^2} w_1 + k_1 k_2 w_1$$
$$= m_2 \frac{d^2}{dt^2} F + (k_1 + k_2) F$$

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Higher-order equations. Physical insight bound to fail.

¿Stored energy, conservation laws, etc.?

Aim

**An effective algebraic representation
of bilinear and quadratic functionals
of the system variables and their derivatives:**

Operations/properties of functionals



algebraic operations/properties of representation

...a **calculus of these functionals!**

Recapitulation

- **Dissipation inequality and equality;**

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- **Dissipation function, storage function, supply rate;**

Recapitulation

- **Dissipation inequality and equality;**
- **Dissipation function, storage function, supply rate;**
- **Algebraic representation of systems needs algebraic representation of functionals.**

Part II: Bilinear- and quadratic differential forms

Outline

Definition

Two-variable polynomial matrices

The calculus of B/QDFs

Bilinear differential forms (BDFs)

$$\Phi := \left\{ \Phi_{k,l} \in \mathbb{R}^{w_1 \times w_2} \right\}_{k,l=0,\dots,L}$$

$$L_\Phi : \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^{w_1}) \times \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^{w_2}) \rightarrow \mathcal{C}^\infty(\mathbb{R}, \mathbb{R})$$

$$L_\Phi(w_1, w_2) := \begin{bmatrix} w_1^\top & \frac{dw_1}{dt}^\top & \dots \end{bmatrix} \begin{bmatrix} \Phi_{0,0} & \Phi_{0,1} & \dots \\ \Phi_{1,0} & \Phi_{1,1} & \dots \\ \vdots & \vdots & \dots \\ \Phi_{k,0} & \Phi_{k,1} & \dots \\ \vdots & \vdots & \dots \end{bmatrix} \begin{bmatrix} w_2 \\ \frac{dw_2}{dt} \\ \vdots \end{bmatrix}$$
$$= \sum_{k,l} \left(\frac{d^k}{dt^k} w_1 \right)^\top \Phi_{k,l} \left(\frac{d^l}{dt^l} w_2 \right)$$

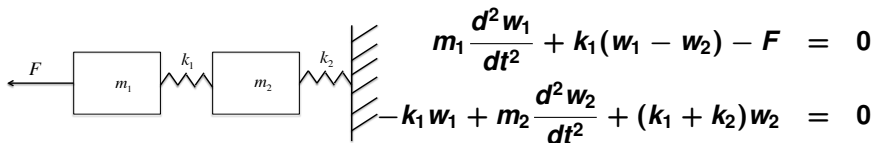
Quadratic differential forms (QDFs)

$\Phi := \{ \Phi_{k,l} \in \mathbb{R}^{w \times w} \}_{k,l=0,\dots,L}$ **symmetric, i.e.** $\Phi_{k,l} = \Phi_{l,k}^\top$

$$Q_\Phi : \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w) \rightarrow \mathcal{C}^\infty(\mathbb{R}, \mathbb{R})$$

$$Q_\Phi(W) := \begin{bmatrix} W^\top & \frac{dW}{dt}^\top & \dots \end{bmatrix} \begin{bmatrix} \Phi_{0,0} & \Phi_{0,1} & \dots \\ \Phi_{1,0} & \Phi_{1,1} & \dots \\ \vdots & \vdots & \dots \\ \Phi_{k,0} & \Phi_{k,1} & \dots \\ \vdots & \vdots & \dots \end{bmatrix} \begin{bmatrix} W \\ \frac{dW}{dt} \\ \vdots \end{bmatrix}$$
$$= \sum_{k,l=0}^L \left(\frac{d^k}{dt^k} W \right)^\top \Phi_{k,l} \left(\frac{d^l}{dt^l} W \right)$$

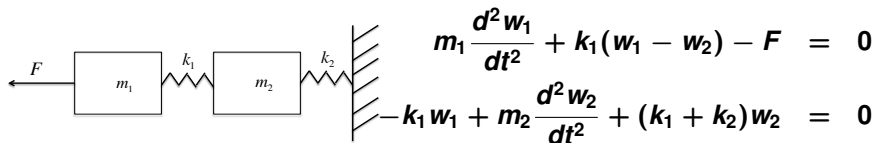
Example: total energy in mechanical system



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Total energy is

$$\frac{1}{2} m_1 \left(\frac{d}{dt} w_1 \right)^2 + \frac{1}{2} m_2 \left(\frac{d}{dt} w_2 \right)^2 + \frac{1}{2} k_1 (w_1 - w_2)^2 + \frac{1}{2} k_2 w_2^2$$

$$= \begin{bmatrix} w_1 & w_2 & F & \frac{d}{dt} w_1 & \frac{d}{dt} w_2 & \frac{d}{dt} F \end{bmatrix} \begin{bmatrix} \frac{1}{2} k_1 & -\frac{1}{2} k_1 & 0 & 0 & 0 & 0 \\ -\frac{1}{2} k_1 & \frac{1}{2} (k_1 + k_2) & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} m_1 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2} m_2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ F \\ \frac{d}{dt} w_1 \\ \frac{d}{dt} w_2 \\ \frac{d}{dt} F \end{bmatrix}$$

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Two-variable polynomial matrices

The calculus of B/QDFs

Two-variable polynomial matrices for BDFs

$$\{\Phi_{k,l} \in \mathbb{R}^{w_1 \times w_2}\}_{k,l=0,\dots,L}$$

$$L_{\Phi}(w_1, w_2) = \sum_{k,l=0}^L \left(\frac{d^k}{dt^k} w_1 \right)^{\top} \Phi_{k,l} \frac{d^l}{dt^l} w_2$$

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$$\Phi(\zeta, \eta) = \sum_{k,l=0}^L \Phi_{k,l} \zeta^k \eta^l$$

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2-variable polynomial matrix associated with L_Φ

Two-variable polynomial matrices for QDFs

$\{\Phi_{k,l} \in \mathbb{R}^{w \times w}\}_{k,l=0,\dots,L}$ **symmetric** ($\Phi_{k,l} = \Phi_{l,k}^\top$)

$$Q_\Phi(w) = \sum_{k,l=0}^L \left(\frac{d^k}{dt^k} w \right)^\top \Phi_{k,l} \frac{d^l}{dt^l} w$$

$$\Phi(\zeta, \eta) = \sum_{k,l=0}^L \Phi_{k,l} \zeta^k \eta^l$$

symmetric: $\Phi(\zeta, \eta) = \Phi(\eta, \zeta)^\top$

Example: total energy in mechanical system

$$Q_E(w_1, w_2, F) =$$

$$\begin{bmatrix} w_1 & w_2 & F & \frac{d}{dt} w_1 & \frac{d}{dt} w_2 & \frac{d}{dt} F \end{bmatrix} \begin{bmatrix} \frac{1}{2} k_1 & -\frac{1}{2} k_1 & 0 & 0 & 0 & 0 \\ -\frac{1}{2} k_1 & \frac{1}{2} (k_1 + k_2) & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} m_1 & 0 & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{2} m_2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ F \\ \frac{d}{dt} w_1 \\ \frac{d}{dt} w_2 \\ \frac{d}{dt} F \end{bmatrix}$$

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The calculus of B/QDFs

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Using powers of ζ and η as placeholders,

B/QDF \leftrightarrow two-variable polynomial matrix

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Using powers of ζ and η as placeholders,

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**Operations
and properties
of B/QDF**



**algebraic
operations/properties
on two-variable matrix**

Differentiation

$\Phi \in \mathbb{R}_s^{w \times w}[\zeta, \eta]$. $\dot{\Phi}$ derivative of Q_Φ :

$$Q_{\dot{\Phi}} : \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w) \rightarrow \mathcal{C}^\infty(\mathbb{R}, \mathbb{R})$$

$$Q_{\dot{\Phi}}(w) := \frac{d}{dt}(Q_\Phi(w))$$

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$$\dot{\Phi}(\zeta, \eta) = (\zeta + \eta)\Phi(\zeta, \eta)$$

Two-variable version of Leibniz's rule

Integration

$\mathfrak{D}(\mathbb{R}, \mathbb{R}^\bullet)$ \mathcal{C}^∞ -compact-support trajectories

$$L_\Phi : \mathfrak{D}(\mathbb{R}, \mathbb{R}^{w_1}) \times \mathfrak{D}(\mathbb{R}, \mathbb{R}^{w_2}) \rightarrow \mathfrak{D}(\mathbb{R}, \mathbb{R})$$

$$\int L_\Phi : \mathfrak{D}(\mathbb{R}, \mathbb{R}^{w_1}) \times \mathfrak{D}(\mathbb{R}, \mathbb{R}^{w_2}) \rightarrow \mathbb{R}$$
$$\int L_\Phi(w_1, w_2) := \int_{-\infty}^{+\infty} L_\Phi(w_1, w_2) dt$$

Analogous for QDFs

Part III: LTI dissipative differential systems

Outline

Characterizations of dissipativity

Dissipation and storage in an algebraic setting

Setting the stage

LTI systems



supply, dissipation, storage
are **quadratic functionals**
of the system variables
and their derivatives

Setting the stage

LTI systems \rightsquigarrow supply, dissipation, storage
are **quadratic functionals**
of the system variables
and their derivatives

Dissipation equality:

$$Q_{\Phi}(w) = Q_{\Delta}(w) + \frac{d}{dt} Q_{\Psi}(w)$$

where $w \in \mathcal{B}$

Setting the stage

Controllable system

$$w = M\left(\frac{d}{dt}\right)\ell \rightsquigarrow M(\xi)$$

Power ('supply rate')

$$Q_\Phi \rightsquigarrow \Phi(\zeta, \eta)$$

Setting the stage

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$$Q_\Phi(w) = Q_\Phi\left(M\left(\frac{d}{dt}\right)\ell\right)$$

$$\Phi'(\zeta, \eta) := M(\zeta)^\top \Phi(\zeta, \eta) M(\eta)$$

Q_Φ' acts on free variable ℓ , i.e. \mathcal{C}^∞

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When is a system dissipative?

Dissipation equality:

$$Q_\Phi = \frac{d}{dt} Q_\Psi + Q_\Delta$$

When is a system dissipative?

Dissipation equality:

$$Q_\Phi = \frac{d}{dt} Q_\Psi + Q_\Delta$$

Integrate along compact-support trajectory:

$$\int_{-\infty}^{+\infty} Q_\Phi(w) dt = Q_\Psi(w) \Big|_{-\infty}^{+\infty} + \int_{-\infty}^{+\infty} Q_\Delta(w) dt$$

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When is a system dissipative?

Dissipation equality:

$$Q_\Phi = \frac{d}{dt} Q_\Psi + Q_\Delta$$

$$\int_{-\infty}^{+\infty} Q_\Phi(w) dt \geq 0$$

for all compact-support trajectories $w \in \mathcal{B}$

When is a system dissipative?

$$\int_{-\infty}^{+\infty} \mathbf{Q}_{\Phi}(w) dt \geq 0$$

for all compact-support trajectories $w \in \mathcal{B}$

If $w = M\left(\frac{d}{dt}\right)\ell$, equivalent to

$$\mathbf{Q}_{\Phi'}(\ell) \geq 0 \text{ for all } \ell \in \mathfrak{C}^{\infty}$$

with $\Phi'(\zeta, \eta) = M(\zeta)^{\top} \Phi(\zeta, \eta) M(\eta)$

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If $\mathbf{w} = \mathbf{M}\left(\frac{d}{dt}\right)\ell$, equivalent to

$$\mathbf{Q}_{\Phi'}(\ell) \geq \mathbf{0} \text{ for all } \ell \in \mathfrak{C}^\infty$$

with $\Phi'(\zeta, \eta) = \mathbf{M}(\zeta)^\top \Phi(\zeta, \eta) \mathbf{M}(\eta)$

Fourier transformation leads to

$$\Phi'(-i\omega, i\omega) = \mathbf{M}(-i\omega)^\top \Phi(-i\omega, i\omega) \mathbf{M}(i\omega) \geq \mathbf{0}$$

for all $\omega \in \mathbb{R}$

When is a system dissipative?

$$\int_{-\infty}^{+\infty} Q_{\Phi}(w) dt \geq 0$$

for all compact-support trajectories $w \in \mathcal{B}$

Fourier transformation leads to

$$\Phi'(-i\omega, i\omega) = M(-i\omega)^{\top} \Phi(-i\omega, i\omega) M(i\omega) \geq 0$$

for all $\omega \in \mathbb{R}$

¡A frequency-domain inequality!

When is a system dissipative?

We just proved:

im $M(\frac{d}{dt})$ is Φ -dissipative

if and only if

$$**M(-i\omega)^\top \Phi(-i\omega, i\omega) M(i\omega) \geq 0 \text{ for all } \omega \in \mathbb{R}**$$

Characterizations of dissipativity

Theorem: The following conditions are equivalent:

- $\int_{-\infty}^{+\infty} Q_{\Phi}(\ell) dt \geq 0$ for all \mathcal{C}^{∞} compact-support ℓ ;
- Q_{Φ} admits a storage function;
- Q_{Φ} admits a dissipation rate

Given Q_{Φ} , storage and dissipation are one-one:

$$\frac{d}{dt} Q_{\Psi} = Q_{\Phi} - Q_{\Delta}$$

$$(\zeta + \eta)\Psi(\zeta, \eta) = \Phi(\zeta, \eta) - \Delta(\zeta, \eta)$$

Example: mechanical systems

$$M \frac{d^2}{dt^2} \mathbf{q} + D \frac{d}{dt} \mathbf{q} + K \mathbf{q} = \mathbf{F} \quad \begin{bmatrix} \mathbf{F} \\ \mathbf{q} \end{bmatrix} = \begin{bmatrix} M \frac{d^2}{dt^2} + D \frac{d}{dt} + K \\ I_3 \end{bmatrix} \ell$$

Example: mechanical systems

$$M \frac{d^2}{dt^2} \mathbf{q} + D \frac{d}{dt} \mathbf{q} + K \mathbf{q} = \mathbf{F} \quad \begin{bmatrix} \mathbf{F} \\ \mathbf{q} \end{bmatrix} = \begin{bmatrix} M \frac{d^2}{dt^2} + D \frac{d}{dt} + K \\ I_3 \end{bmatrix} \ell$$

Supply rate: power

$$\mathbf{F}^\top \left(\frac{d}{dt} \mathbf{q} \right) = \left(M \frac{d^2}{dt^2} \ell + D \frac{d}{dt} \ell + K \ell \right)^\top \left(\frac{d}{dt} \ell \right)$$

corresponding to

$$\Phi(\zeta, \eta) = \frac{1}{2} (M \zeta^2 + D \zeta + K)^\top \eta + \frac{1}{2} \zeta (M \eta^2 + D \eta + K)$$

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$$M \frac{d^2}{dt^2} \mathbf{q} + D \frac{d}{dt} \mathbf{q} + K \mathbf{q} = \mathbf{F} \quad \begin{bmatrix} \mathbf{F} \\ \mathbf{q} \end{bmatrix} = \begin{bmatrix} M \frac{d^2}{dt^2} + D \frac{d}{dt} + K \\ I_3 \end{bmatrix} \ell$$

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$$\Phi(\zeta, \eta) = \frac{1}{2} (M\zeta^2 + D\zeta + K)^\top \eta + \frac{1}{2} \zeta (M\eta^2 + D\eta + K)$$

If dissipation inequality

$$\Phi(\zeta, \eta) = (\zeta + \eta) \Psi(\zeta, \eta) + \Delta(\zeta, \eta)$$

holds, then

$$\Phi(-\xi, \xi) = -\frac{1}{2} \xi^2 (D^\top + D) = \Delta(-\xi, \xi)$$

$$\implies \Delta(\zeta, \eta) = \frac{1}{2} (D^\top + D) \zeta \eta$$

Spectral factorization of $\Phi(-\xi, \xi)$ is key

Example: mechanical systems

$$M \frac{d^2}{dt^2} \mathbf{q} + D \frac{d}{dt} \mathbf{q} + K \mathbf{q} = \mathbf{F} \quad \begin{bmatrix} \mathbf{F} \\ \mathbf{q} \end{bmatrix} = \begin{bmatrix} M \frac{d^2}{dt^2} + D \frac{d}{dt} + K \\ I_3 \end{bmatrix} \ell$$

$$\Phi(\zeta, \eta) = \frac{1}{2} (M \zeta^2 + D \zeta + K)^\top \eta + \frac{1}{2} \zeta (M \eta^2 + D \eta + K)$$

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Example: mechanical systems

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$$\Delta(\zeta, \eta) = \frac{1}{2} (D^\top + D) \zeta \eta$$

Storage function

$$\Psi(\zeta, \eta) = \frac{\Phi(\zeta, \eta) - \Delta(\zeta, \eta)}{\zeta + \eta} = \frac{1}{2} M \zeta \eta + \frac{1}{2} K$$

Total energy

Example: mechanical systems

$$M \frac{d^2}{dt^2} \mathbf{q} + D \frac{d}{dt} \mathbf{q} + K \mathbf{q} = \mathbf{F} \quad \begin{bmatrix} \mathbf{F} \\ \mathbf{q} \end{bmatrix} = \begin{bmatrix} M \frac{d^2}{dt^2} + D \frac{d}{dt} + K \\ I_3 \end{bmatrix} \ell$$

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Physically correct: $\frac{d}{dt} Q_\Psi + Q_\Delta$ equals

$$\underbrace{\left(\frac{d^2}{dt^2} \mathbf{q} \right)^\top M \frac{d}{dt} \mathbf{q} + \mathbf{q}^\top K \frac{d}{dt} \mathbf{q} + \frac{1}{2} \left(\frac{d}{dt} \mathbf{q} \right)^\top (D + D^\top) \frac{d}{dt} \mathbf{q}}_{\frac{d}{dt} \left[\frac{1}{2} \left(\frac{d}{dt} \mathbf{q} \right)^\top M \frac{d}{dt} \mathbf{q} + \frac{1}{2} \mathbf{q}^\top K \mathbf{q} \right]}$$

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Supply rate equals

$$\mathbf{F}^\top \frac{d}{dt} \mathbf{q} = \left[\left(\frac{d^2}{dt^2} \mathbf{q} \right)^\top M + \left(\frac{d}{dt} \mathbf{q} \right)^\top D^\top + \mathbf{q}^\top K \right] \frac{d}{dt} \mathbf{q}$$

Outline

Characterizations of dissipativity

Dissipation and storage in an algebraic setting

Dissipation functions and spectral factorization

$$(\zeta + \eta)\Psi(\zeta, \eta) + \Delta(\zeta, \eta) = \Phi(\zeta, \eta)$$

¿How to compute Δ and Ψ ?

Dissipation functions and spectral factorization

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¿How to compute Δ and Ψ ?

Let $\zeta = -\xi, \eta = \xi$; then $\Delta(-\xi, \xi) = \Phi(-\xi, \xi)$

Dissipation functions and spectral factorization

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Let $\zeta = -\xi$, $\eta = \xi$; then $\Delta(-\xi, \xi) = \Phi(-\xi, \xi)$

Also, $Q_{\Delta}(\ell) \geq 0$ for all $\ell \in \mathcal{C}^{\infty}(\mathbb{R}, \mathbb{R}^{\bullet}) \implies$
there exists square $D \in \mathbb{R}^{\bullet \times \bullet}[\xi]$ such that

$$\Delta(\zeta, \eta) = D(\zeta)^{\top} D(\eta)$$

Dissipation functions and spectral factorization

$$(\zeta + \eta)\Psi(\zeta, \eta) + \Delta(\zeta, \eta) = \Phi(\zeta, \eta)$$

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there exists square $D \in \mathbb{R}^{\bullet \times \bullet}[\xi]$ such that

$$\Delta(\zeta, \eta) = D(\zeta)^\top D(\eta)$$

Spectral factorization: given $\Phi(-\xi, \xi)$, find square matrix D s.t.

$$\Phi(-\xi, \xi) = D(-\xi)^\top D(\xi)$$

Dissipation functions and spectral factorization

$$(\zeta + \eta)\Psi(\zeta, \eta) + \Delta(\zeta, \eta) = \Phi(\zeta, \eta)$$

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Let $\zeta = -\xi$, $\eta = \xi$; then $\Delta(-\xi, \xi) = \Phi(-\xi, \xi)$

Spectral factorization: given $\Phi(-\xi, \xi)$, find square matrix D s.t.

$$\Phi(-\xi, \xi) = D(-\xi)^\top D(\xi)$$

Solvable if and only if $\Phi(-i\omega, i\omega) \geq 0$ for all $\omega \in \mathbb{R}$.

¡Frequency domain condition for dissipativity!

Dissipation functions and spectral factorization

$$(\zeta + \eta)\Psi(\zeta, \eta) + \Delta(\zeta, \eta) = \Phi(\zeta, \eta)$$

¿How to compute Δ and Ψ ?

Spectral factorize $\Phi(-\xi, \xi) = D(-\xi)^\top D(\xi)$, define

$$\Delta(\zeta, \eta) := D(\zeta)^\top D(\eta)$$

Dissipation functions and spectral factorization

$$(\zeta + \eta)\Psi(\zeta, \eta) + \Delta(\zeta, \eta) = \Phi(\zeta, \eta)$$

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Spectral factorize $\Phi(-\xi, \xi) = D(-\xi)^\top D(\xi)$, define

$$\Delta(\zeta, \eta) := D(\zeta)^\top D(\eta)$$

$\Phi(-\xi, \xi) = \Delta(-\xi, \xi) \implies$ there exists $\Psi(\zeta, \eta)$ s.t.

$$\Phi(\zeta, \eta) - \Delta(\zeta, \eta) = (\zeta + \eta)\Psi(\zeta, \eta)$$

Then storage function is

$$\Psi(\zeta, \eta) = \frac{\Phi(\zeta, \eta) - \Delta(\zeta, \eta)}{\zeta + \eta}$$

Remarks

- **Many ways of spectral factorizing the same matrix**
 - ~> **many dissipation functions**
 - ~> **many storage functions.**

Remarks

- **Many ways of spectral factorizing the same matrix**
 - \rightsquigarrow many dissipation functions
 - \rightsquigarrow many storage functions.

- **Set of storage functions is convex:**

Q_{ψ_1}, Q_{ψ_2} storage functions and $\alpha \in [0, 1]$
 $\implies \alpha Q_{\psi_1} + (1 - \alpha) Q_{\psi_2}$ is storage function

Maximal and minimal storage functions

Let $\mathcal{B} \in \mathcal{L}^w$ be controllable and Φ -dissipative. There exist storage functions Q_{ψ_-} and Q_{ψ_+} such that for any storage function Q_{ψ} it holds

$$Q_{\psi_-} \leq Q_{\psi} \leq Q_{\psi_+}$$

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Q_{ψ_-} is minimal-, Q_{ψ_+} is maximal storage function

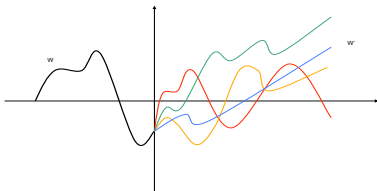
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Q_{ψ_-} is **available storage**:

$$Q_{\psi_-}(w)(0) = \sup_{\substack{w' \text{ s.t.} \\ w \wedge w' \in \mathcal{B}}} \left(- \int_0^{\infty} Q_{\Phi}(w') dt \right)$$



Maximum amount of energy extractable from system.

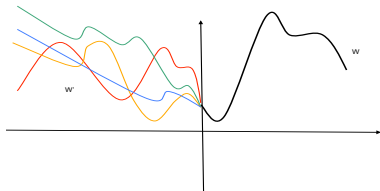
Maximal and minimal storage functions

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$$Q_{\psi_-} \leq Q_{\psi} \leq Q_{\psi_+}$$

Q_{ψ_+} is **required supply**:

$$Q_{\psi_+}(w)(0) = \inf_{\substack{w' \text{ s.t.} \\ w' \wedge w \in \mathcal{B}}} \left(\int_{-\infty}^0 Q_{\Phi}(w') dt \right)$$



Minimum energy needed to produce w from $t = 0$

Spectral factorization and extremal storage functions

If $\det \Phi(-\xi, \xi) \neq 0$ and $\Phi(-i\omega, i\omega) \geq 0$ for all $\omega \in \mathbb{R}$,
there exist H, A s.t.

$$\Phi(-\xi, \xi) = H(-\xi)^\top H(\xi) = A(-\xi)^\top A(\xi)$$

where

$$\det(H(\lambda)) = 0 \implies \lambda \in \mathbb{C}_-^0 \text{ ("semi-Hurwitz polynomial")}$$

$$\det(A(\lambda)) = 0 \implies \lambda \in \mathbb{C}_+^0 \text{ ("semi-anti-Hurwitz polynomial")}$$

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In this case,

$$\Psi_-(\zeta, \eta) = \frac{\Phi(\zeta, \eta) - H(\zeta)^\top H(\eta)}{\zeta + \eta}$$

$$\Psi_+(\zeta, \eta) = \frac{\Phi(\zeta, \eta) - A(\zeta)^\top A(\eta)}{\zeta + \eta}$$

Storage functions and the state

Circuit theory folklore: state variables are associated with energy storing elements (capacitors, inductors)

Storage functions and the state

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Physics: potential energy in a field dependent on position (and velocity/acceleration)

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Circuit theory folklore: state variables are associated with energy storing elements (capacitors, inductors)

Physics: potential energy in a field dependent on position (and velocity/acceleration)

¿Can we give rational foundation to the intuition that “storage” is related with “memory”?

Storage functions and the state

Theorem: Let $\Sigma = \Sigma^\top \in \mathbb{R}^{w \times w}$ be nonsingular. Assume that $\mathcal{B} = \text{im} \left(M \left(\frac{d}{dt} \right) \right)$ is Σ -dissipative.

Let $\Psi \in \mathbb{R}^{w \times w}[\zeta, \eta]$ be a storage function, and let $X \in \mathbb{R}^{\bullet \times w}[\xi]$ be a state map for \mathcal{B} .

Then $\exists K = K^\top \in \mathbb{R}^{\bullet \times \bullet}$, $E = E^\top \in \mathbb{R}^{\bullet \times \bullet}$ such that

$$\begin{aligned} \Psi(\zeta, \eta) &= X(\zeta)^\top K X(\eta) \\ \Delta(\zeta, \eta) &= \begin{bmatrix} M(\zeta) \\ X(\zeta) \end{bmatrix}^\top E \begin{bmatrix} M(\eta) \\ X(\eta) \end{bmatrix} \end{aligned}$$

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Let $\Psi \in \mathbb{R}^{w \times w}[\zeta, \eta]$ be a storage function, and let $X \in \mathbb{R}^{o \times w}[\xi]$ be a state map for \mathcal{B} .

Then $\exists K = K^\top \in \mathbb{R}^{o \times o}$, $E = E^\top \in \mathbb{R}^{o \times o}$ such that

$$\begin{aligned} \Psi(\zeta, \eta) &= X(\zeta)^\top K X(\eta) \\ \Delta(\zeta, \eta) &= \begin{bmatrix} M(\zeta) \\ X(\zeta) \end{bmatrix}^\top E \begin{bmatrix} M(\eta) \\ X(\eta) \end{bmatrix} \end{aligned}$$

**! The storage function
is a quadratic function of the state!**

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**! The dissipation function
is a quadratic function of the state and of the input!**

Recapitulation

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- **Characterization of dissipativity, dissipation and storage functions;**

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Recapitulation

- **Characterization of dissipativity, dissipation and storage functions;**
- **Spectral factorization and storage functions;**
- **Extremal storage functions;**
- **Storage function is a function of the state.**

Part IV: Dissipativity and state representations

Outline

The linear matrix inequality

The algebraic Riccati equation

Setting the stage

$$\mathcal{B} = \left\{ (x, u) \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^{n+m}) \mid \frac{d}{dt}x = Ax + Bu \right\}$$

\mathcal{B} controllable $\iff (A, B)$ controllable

Setting the stage

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\mathcal{B} controllable $\iff (A, B)$ controllable

Observable image representation of \mathcal{B} :

$$\begin{bmatrix} x \\ u \end{bmatrix} = \begin{bmatrix} X(\frac{d}{dt}) \\ U(\frac{d}{dt}) \end{bmatrix} \ell$$

Setting the stage

Observable image representation of \mathcal{B} :

$$\begin{bmatrix} \mathbf{x} \\ \mathbf{u} \end{bmatrix} = \begin{bmatrix} \mathbf{X}(\frac{d}{dt}) \\ \mathbf{U}(\frac{d}{dt}) \end{bmatrix} \ell$$

\mathcal{B} is dissipative with respect to

$$\Sigma := \begin{bmatrix} \mathbf{Q} & \mathbf{S}^\top \\ \mathbf{S} & \mathbf{R} \end{bmatrix} \rightsquigarrow \mathbf{x}^\top \mathbf{Q} \mathbf{x} + 2\mathbf{x}^\top \mathbf{S}^\top \mathbf{u} + \mathbf{u}^\top \mathbf{R} \mathbf{u}$$

Setting the stage

Observable image representation of \mathcal{B} :

$$\begin{bmatrix} \mathbf{x} \\ \mathbf{u} \end{bmatrix} = \begin{bmatrix} \mathbf{X}(\frac{d}{dt}) \\ \mathbf{U}(\frac{d}{dt}) \end{bmatrix} \ell$$

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Leads to

$$\Phi(\zeta, \eta) := \begin{bmatrix} \mathbf{X}(\zeta)^\top & \mathbf{U}(\zeta)^\top \end{bmatrix} \begin{bmatrix} \mathbf{Q} & \mathbf{S}^\top \\ \mathbf{S} & \mathbf{R} \end{bmatrix} \begin{bmatrix} \mathbf{X}(\eta) \\ \mathbf{U}(\eta) \end{bmatrix}$$

acting on $\mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^m)$.

The linear matrix inequality

Theorem. The following conditions are equivalent:

1. \mathcal{B} is Σ -dissipative;
2. $\int_{-\infty}^{+\infty} \mathbf{Q}_\phi \geq \mathbf{0}$;
3. $\exists \mathbf{K} = \mathbf{K}^\top \in \mathbb{R}^n$ s.t. **linear matrix inequality (LMI)**

$$\begin{bmatrix} \mathbf{Q} - \mathbf{A}^\top \mathbf{K} - \mathbf{K} \mathbf{A} & -\mathbf{K} \mathbf{B} + \mathbf{S}^\top \\ -\mathbf{B}^\top \mathbf{K} + \mathbf{S} & \mathbf{R} \end{bmatrix} \geq \mathbf{0}$$

holds.

If any of the above conditions hold, then $x^\top \mathbf{K} x$ is a storage function for \mathcal{B} .

Outline

The linear matrix inequality

The algebraic Riccati equation

The algebraic Riccati equation

Assume $\det \Phi(-\xi, \xi) \neq 0$. Then there exists F of full row rank m s.t.

$$\begin{bmatrix} Q - A^\top K - KA & -KB + S^\top \\ -B^\top K + S & R \end{bmatrix} = F^\top F$$

The algebraic Riccati equation

Assume $\det \Phi(-\xi, \xi) \neq 0$. Then there exists F of full row rank m s.t.

$$\begin{bmatrix} Q - A^\top K - KA & -KB + S^\top \\ -B^\top K + S & R \end{bmatrix} = F^\top F$$

Assume $R > 0$, and write Schur complement of R :

$$Q - A^\top K - KA - (-KB + S^\top)R^{-1}(-BK + S) = 0$$

The algebraic Riccati equation

Assume $\det \Phi(-\xi, \xi) \neq 0$. Then there exists F of full row rank m s.t.

$$\begin{bmatrix} Q - A^\top K - KA & -KB + S^\top \\ -B^\top K + S & R \end{bmatrix} = F^\top F$$

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Algebraic Riccati equation



Remarks

- **State-space case as special case;**
- **First-order aspect and other (historical, etc.) reasons \rightsquigarrow efficient algorithms;**
- **Optimal control, filtering, etc. applications of ARE.**

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- **First principles approach to dissipation theory;**
- **Two-variable polynomial matrices and the calculus of bilinear- and differential forms;**
- **Answers (algorithmic!) to: “when is a system dissipative?”, “how to compute a dissipation function?”, etc.**
- **Algebraic Riccati equation, LMIs, etc. as *special case* of higher-order approach.**