

Solution to the exercises for lectures 12 and 14

Exercise 1

- 1.1** From the fact that $X(\xi)U(\xi)^{-1} = (\xi I - A)^{-1}B$ it follows that $\xi X(\xi) = AX(\xi) + BU(\xi)$. Consequently

$$(\zeta + \eta)X(\zeta)^T K X(\eta) = X(\zeta)^T A^T K X(\eta) + U(\zeta)^T B^T K X(\eta) + X(\zeta)^T K A X(\eta) + X(\zeta)^T K B U(\eta),$$

which can be rewritten as

$$\begin{pmatrix} X(\zeta)^T & U(\zeta)^T \end{pmatrix} \begin{pmatrix} A^T K + K A & K B \\ B^T K & 0 \end{pmatrix} \begin{pmatrix} X(\eta) \\ U(\eta) \end{pmatrix}.$$

- 1.2** Using the result proven in the previous point, and the definition of $\Phi(\zeta, \eta)$ given in the text in order to arrive at

$$\begin{aligned} & (\zeta + \eta)X(\zeta)^T K X(\eta) = \Phi(\zeta, \eta) \\ & - \begin{pmatrix} X(\zeta)^T & U(\zeta)^T \end{pmatrix} \begin{pmatrix} Q - A^T K - K A & -K B + S^T \\ -B^T K + S & R \end{pmatrix} \begin{pmatrix} X(\eta) \\ U(\eta) \end{pmatrix}. \end{aligned}$$

We now prove the lemma suggested in the hint. This will lead us immediately to the conclusion.

Let $(x_0, u_0) \in \mathbb{R}^n \times \mathbb{R}^m$. Let $\tilde{u} \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^m)$ be such that $\tilde{u}(0) = u_0$. Consider the differential equation $\dot{x} = Ax + B\tilde{u}$, $x(0) = x_0$, and let $\tilde{x} \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^n)$ be its solution. Evidently, $\text{col}(\tilde{x}, \tilde{u}) \in \text{im} \begin{pmatrix} X(\frac{d}{dt}) \\ U(\frac{d}{dt}) \end{pmatrix}$, so there exists $\ell \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^n)$ such that

$$\begin{pmatrix} \tilde{x} \\ \tilde{u} \end{pmatrix} = \begin{pmatrix} X(\frac{d}{dt}) \\ U(\frac{d}{dt}) \end{pmatrix} \ell.$$

Consequently,

$$\begin{pmatrix} x_0 \\ u_0 \end{pmatrix} = \begin{pmatrix} \tilde{x}(0) \\ \tilde{u}(0) \end{pmatrix} = \begin{pmatrix} (X(\frac{d}{dt})\ell)(0) \\ (U(\frac{d}{dt})\ell)(0) \end{pmatrix}.$$

The surjectivity of the map $\ell \mapsto \text{col}((X(\frac{d}{dt})\ell)(0), (U(\frac{d}{dt})\ell)(0))$ shows that the QDF induced by

$$\begin{pmatrix} X(\zeta)^T & U(\zeta)^T \end{pmatrix} \begin{pmatrix} Q - A^T K - K A & -K B + S^T \\ -B^T K + S & R \end{pmatrix} \begin{pmatrix} X(\eta) \\ U(\eta) \end{pmatrix}$$

is nonnegative (and consequently, it is a *bona fide* dissipation function) if and only if

$$\begin{pmatrix} Q - A^T K - K A & -K B + S^T \\ -B^T K + S & R \end{pmatrix}$$

is nonnegative.

- 1.3** H is semi-Hurwitz, meaning its determinant is a semi-Hurwitz polynomial, thus nonzero. Now if $H \in \mathbb{R}^{m \times m}[\xi]$ is a nonsingular polynomial matrix, then its rows are linearly independent over the field of rational functions, and *a fortiori* over \mathbb{R} . It follows from this that also the rows of \tilde{H} are linearly independent. Consequently, $\tilde{H}^T \tilde{H}$ has rank m . By the result suggested in the hint for Question 1.1, the mapping

$$\ell \mapsto \text{col}\left(\left(X\left(\frac{d}{dt}\right)\ell\right)(0), \left(U\left(\frac{d}{dt}\right)\ell\right)(0)\right)$$

is surjective. It follows that the coefficient matrix of $\text{col}(X(\xi), U(\xi))$ has full row rank. Consequently, the matrix

$$\begin{pmatrix} Q - A^T K - K A & -K B + S^T \\ -B^T K + S & R \end{pmatrix}$$

has rank m .

- 1.4** The answer follows immediately from the hint given.

Exercise 2

- 2.1** We prove only the “only if” part, since the other implication follows easily from the hint.

That \mathcal{V} is a linear space follows easily from the fact that \mathfrak{B} is a linear subspace of the set of sequences (x, w) . Now if \mathcal{V} is a linear space, then it admits a representation as the kernel of a matrix. In order to conclude the proof, partition the matrix according to the partition of the vectors of \mathcal{V} as

$$[E \quad F \quad G].$$

- 2.2 2.2.a** The easiest way is to write the matrix $R(\xi)$ as

$$R(\xi) = \text{diag}(\xi^{\delta_i})_{i=1, \dots, p} R_{\text{hc}} + R'(\xi)$$

where $R'(\xi)$ is a matrix whose row-degrees are strictly lower than those of $R(\xi)$. Since R_{hc} is full row rank, it has a nonsingular submatrix P . It is readily seen that the submatrix of $R(\xi)$ consisting of the columns corresponding to those of P has determinant

$$\det(P)\xi^{\sum_{i=1}^p \delta_i} + \text{terms of lower order}$$

Observe also that any other selection of a square submatrix of $R(\xi)$ (and consequently of a minor of $R(\xi)$) corresponds to a selection of a square submatrix of R_{hc} . If this latter submatrix is nonsingular, it follows from the argument used before that the determinant of the corresponding square submatrix of $R(\xi)$ has degree $\sum_{i=1}^p \delta_i$; otherwise, this determinant will have lower degree.

2.2.b Use the representation

$$R(\xi) = \text{diag}(\xi^{\delta_i})_{i=1, \dots, p} R_{\text{hc}} + R'(\xi)$$

and apply the shift-and-cut operation to $R(\xi)$. After k iterations of the shift-and-cut operation, the only nonzero rows of $\sigma_+^k(R)$ are those corresponding to row degrees higher than or equal to k . Also, because of the fact that R_{hc} has full row rank, the nonzero rows of $\sigma_+^k(R)$ are linearly independent. This yields the claim, since there are exactly δ_i nonzero shift-and-cuts of the i -th row of R .

2.2.c The claim follows straightforwardly from the result proved in 2.2.b.

Exercise 3

3.1 From the dissipation equality we know that $\Phi(-\xi, \xi) = \Delta(-\xi, \xi)$, with Δ the two-variable 1×1 polynomial matrix inducing the dissipation rate. The supply rate $Q_\Phi(w, F) = F \frac{d}{dt} w$ is represented by the two-variable polynomial matrix

$$\Phi(\zeta, \eta) = \begin{bmatrix} 0 & \frac{1}{2}\zeta \\ \frac{1}{2}\eta & 0 \end{bmatrix}.$$

Working with an image representation of the system allows us to avoid studying the QDFs along the behavior of the system, and to consider them acting on the whole \mathcal{C}^∞ instead. An observable image representation of the system is induced by

$$M(\xi) = \begin{bmatrix} 1 \\ m\xi^2 + c\xi + k \end{bmatrix}$$

The QDF $Q_{\Phi'}$ acting on the latent variable ℓ , such that $Q_{\Phi'}(\ell) = Q_\Phi(w)$ for all w and ℓ related by $w = M\left(\frac{d}{dt}\right)\ell$ is induced by the two-variable polynomial

$$\begin{aligned} \Phi'(\zeta, \eta) &= M(\zeta)^\top \Phi(\zeta, \eta) M(\eta) \\ &= \eta \frac{k}{2} + c\eta\zeta + \zeta \frac{k}{2} + \frac{1}{2}m\eta^2\zeta + \frac{1}{2}m\zeta^2\eta \end{aligned}$$

In order to find the dissipation function, we first compute

$$\Phi'(-\xi, \xi) = -c\xi^2$$

Notice that $\Phi'(-i\omega, i\omega) \geq 0$ for all $\omega \in \mathbb{R}$, and consequently that a spectral factorization of this polynomial exists. It is straightforward to compute it as

$$\Phi'(-\xi, \xi) = (-\sqrt{c}\xi) (\sqrt{c}\xi)$$

Note that this is the only possible factorization of the polynomial as $p(-\xi)p(\xi)$; conclude then that the (only) dissipation function is

$$\sqrt{c}\zeta\sqrt{c}\eta = c\zeta\eta$$

In order to see what the physical interpretation of this dissipation function is, notice that the latent variable ℓ in the image representation equals the displacement w of the mass- consequently this dissipation function corresponds to

$$c \left(\frac{d}{dt} w \right)^2.$$

Now the dissipation equality states that

$$\Phi'(\zeta, \eta) - \Delta(\zeta, \eta) = (\zeta + \eta)\Psi(\zeta, \eta)$$

with Q_Ψ being the storage function corresponding to Q_Δ . In the case at hand

$$\left(\eta \frac{k}{2} + c\eta\zeta + \zeta \frac{k}{2} + \frac{1}{2}m\eta^2\zeta + \frac{1}{2}m\zeta^2\eta \right) - (c\zeta\eta) = (\zeta + \eta) \left(\frac{k}{2} + \frac{1}{2}m\eta\zeta \right)$$

3.2 3.2.a,3.2.b The two-variable polynomials corresponding to the kinetic, respectively potential energy are:

$$\begin{aligned} E_{kin}(\zeta, \eta) &= \frac{1}{2}m\eta\zeta \\ E_{pot}(\zeta, \eta) &= \frac{k}{2} \end{aligned}$$

These two-variable polynomials act on the external variable w of the system described by

$$m \frac{d^2}{dt^2} w + c \frac{d}{dt} w + cw = 0$$

The total energy is induced by $E(\zeta, \eta) = E_{kin}(\zeta, \eta) + E_{pot}(\zeta, \eta) = \frac{1}{2}m\eta\zeta + \frac{k}{2}$. The dissipated energy is $c \left(\frac{d}{dt} w \right)^2$, corresponding to the two-variable polynomial $c\zeta\eta$.

3.2.c The derivative of the total energy is

$$\begin{aligned}
\frac{d}{dt} \left(\frac{1}{2} m \left(\frac{d}{dt} w \right)^2 + \frac{k}{2} w^2 \right) &= m \frac{d}{dt} w \frac{d^2}{dt^2} w + k w \frac{d}{dt} w \\
&= \left(m \frac{d^2}{dt^2} w + k w \right) \frac{d}{dt} w \\
&= \left(m \frac{d^2}{dt^2} w + k w + c \frac{d}{dt} w \right) \frac{d}{dt} w \\
&\quad - c \left(\frac{d}{dt} w \right)^2
\end{aligned}$$

Note that since the equation governing the behavior of the system is $m \frac{d^2}{dt^2} w + k w + c \frac{d}{dt} w = 0$, it follows that along the trajectories of the system the derivative of the total energy is indeed equal to $-c \left(\frac{d}{dt} w \right)^2$.

3.2.d In polynomial terms: the derivative of the total energy is induced by

$$\begin{aligned}
(\zeta + \eta) \left(\frac{1}{2} m \eta \zeta + \frac{k}{2} \right) &= \left(\frac{1}{2} m \eta \zeta^2 + \frac{k}{2} \eta \right) + \left(\frac{1}{2} m \eta^2 \zeta + \frac{k}{2} \zeta \right) \\
&= \frac{1}{2} \left(m \zeta^2 + \frac{k}{2} \right) \eta + \zeta \frac{1}{2} \left(m \eta^2 + \frac{k}{2} \right) \\
&= \frac{1}{2} \left(m \zeta^2 + \frac{k}{2} + c \zeta \right) \eta + \zeta \frac{1}{2} \left(m \eta^2 + \frac{k}{2} + c \eta \right) - c \zeta \eta
\end{aligned}$$

and in the first two terms of the last expression we recognize the “tail” corresponding to the kernel representation of the system

$$m \xi^2 + c \xi + k.$$

In general, the computations involved are not easy to carry out with pen and paper. However, Gröbner bases techniques can be used on software packages for symbolic computation for this purpose.

3.2e Integrating:

$$\int_0^T - \left(D \left(\frac{d}{dt} \right) w \right)^\top \left(D \left(\frac{d}{dt} \right) w \right) dt = Q_\Psi(w)(T) - Q_\Psi(w)(0)$$

Since $Q_\Psi(w) \geq 0$ for all $w \in \mathfrak{B}$, it follows from this equality that

$$\int_0^T - \left(D \left(\frac{d}{dt} \right) w \right)^\top \left(D \left(\frac{d}{dt} \right) w \right) dt \geq -Q_\Psi(w)(0)$$

Since this inequality holds for all $T \in \mathbb{R}_+$, it follows that

$$\int_0^\infty \left(D \left(\frac{d}{dt} \right) w \right)^\top \left(D \left(\frac{d}{dt} \right) w \right) dt$$

is finite. Now an argument by contradiction will lead us to prove the claim. Indeed, assume that $ve^{\lambda t}$ is (the value at t of) a trajectory in \mathfrak{B} , with $v \in \mathbb{C}^w$, $v \neq 0$. Observe that then $R(\lambda)ve^{\lambda t} = 0$ for all t , equivalently $R(\lambda)v = 0$.

Now $D\left(\frac{d}{dt}\right)ve^{\lambda t} = D(\lambda)ve^{\lambda t}$, and the integral

$$\int_0^\infty \left(D\left(\frac{d}{dt}\right)w \right)^\top \left(D\left(\frac{d}{dt}\right)w \right) dt$$

can only be finite if $\lambda \in \mathbb{R}_-$, or if $D(\lambda)v = 0$. In the latter case though, it would hold

$$\begin{bmatrix} R(\lambda) \\ D(\lambda) \end{bmatrix} v = 0$$

a contradiction.

Exercise 4

Consider the behavior described in kernel form by the equation

$$p\left(\frac{d}{dt}\right)y = q\left(\frac{d}{dt}\right)u$$

where

$$\begin{aligned} p(\xi) &= p_0 + p_1\xi + \dots + p_n\xi^n \\ q(\xi) &= q_0 + q_1\xi + \dots + q_n\xi^n \end{aligned}$$

4.1 4.1.a

$$X(\xi) = \begin{bmatrix} p_1 + \dots + p_n\xi^{n-1} & -q_1 - \dots - q_n\xi^{n-1} \\ \vdots & \vdots \\ p_n & -q_n \end{bmatrix}$$

4.1.b The matrix induces a minimal state map since its rows are linearly independent (and of course generate the space $\Xi_R \pmod{R}$).

4.1.c You can check that the equations

$$\begin{aligned} \xi X(\xi) &= AX(\xi) + B \begin{bmatrix} 0 & 1 \end{bmatrix} + F(\xi)R(\xi) \\ \begin{bmatrix} 1 & 0 \end{bmatrix} &= CX(\xi) + D \begin{bmatrix} 0 & 1 \end{bmatrix} + G(\xi)R(\xi) \end{aligned}$$

hold, with

$$F(\xi) = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \text{and} \quad G(\xi) = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

4.1.d The easiest way to obtain the answer is to proceed as follows.

If we perform a nonsingular transformation $x \rightsquigarrow Tx$ of the state variable, and if the state equations are

$$\begin{aligned}\frac{d}{dt}x &= Ax + Bu \\ y &= Cx + Du\end{aligned}$$

then the equations in the new state space basis are

$$\begin{aligned}\frac{d}{dt}Tx &= TAT^{-1}Tx + TBu \\ y &= CT^{-1}Tx + Du\end{aligned}$$

and consequently the new matrices are $A' = TAT^{-1}$, $B' = TB$, $C' = CT^{-1}$, $D' = D$. Apply this now with $T = \Pi$.

4.2 4.2.a The rows of $X(\xi)$ are evidently linearly independent. If we prove that they span the space $\Xi_R \pmod{R}$, we will have shown that the matrix $X(\xi)$ is a minimal state map. In order to do this, compare the coefficients of equal powers of ξ in

$$q(\xi) = (h_0 + h_1\xi^{-1} + \dots)p(\xi)$$

to conclude that

$$q_k = \sum_{i=0}^{n-k} h_i p_{k+i}$$

$k = 0, \dots, n$. From these equalities it follows that if we call $X'(\xi)$ the state map discussed in 4.1.a, then the following relation exists between it and $X(\xi)$:

$$X'(\xi) = \begin{bmatrix} p_1 & \dots & \dots & \dots & p_{n-1} & p_n \\ \vdots & \vdots & \vdots & \vdots & \dots & \vdots \\ p_{n-1} & p_n & 0 & 0 & \dots & 0 \\ p_n & 0 & 0 & 0 & \dots & 0 \end{bmatrix} X(\xi)$$

Observe that this matrix is nonsingular since $p_n \neq 0$. Now use the fact that the rows of the matrix $X(\xi)$ span $\Xi_R \pmod{R}$ in order to conclude that also the rows of $X'(\xi)$ have the same property.

4.2.b Proceeding as described in 4.1.d, we conclude that the new matrices are $A' = TAT^{-1}$, $B' = TB$, $C' = CT^{-1}$, $D' = D$, where

$$T = \begin{bmatrix} p_1 & \dots & \dots & \dots & p_{n-1} & p_n \\ \vdots & \vdots & \vdots & \vdots & \dots & \vdots \\ p_{n-1} & p_n & 0 & 0 & \dots & 0 \\ p_n & 0 & 0 & 0 & \dots & 0 \end{bmatrix}$$