

When is a Linear System Optimal?

Jan C. Willems*

The following problem was presented during the open problem session. Its title is taken from a well-known seminal paper [1] by R.E. Kalman. The questions posed in [1] and here are similar in spirit, but the setting is quite different.

Let $\Phi \in \mathbb{R}^{w \times w}(\zeta, \eta)$, $\Phi(\zeta, \eta) = \sum_{k,\ell} \Phi_{k,\ell} \zeta^k \eta^\ell$, with $\Phi_{k,\ell} = \Phi_{\ell,k}^\top \in \mathbb{R}^{w \times w}$, hence $\Phi = \Phi^*$, where $\Phi^*(\zeta, \eta) := \Phi(\eta, \zeta)^\top$. Denote by Q_Φ the ‘quadratic differential form’ [5] which maps as follows

$$w \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w) \mapsto \sum_{k,\ell} \left(\frac{d^k}{dt^k} w \right)^\top \Phi_{k,\ell} \left(\frac{d^\ell}{dt^\ell} w \right) \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}).$$

Consider for $w, \Delta \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$, with Δ of compact support, the integral

$$\int_{-\infty}^{\infty} (Q_\Phi(w + \Delta) - Q_\Phi(w)) dt. \quad (1)$$

Expand (1) in a term which is bilinear in w, Δ , and one which is quadratic in Δ . We obtain

$$(1) = \int_{-\infty}^{\infty} \Delta^\top \left(\Phi \left(-\frac{d}{dt}, \frac{d}{dt} \right) w \right) dt + \int_{-\infty}^{\infty} Q_\Phi(\Delta) dt.$$

The trajectory $w \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ is said to be *stationary* with respect to Φ , relative to variations Δ , if the linear term in Δ in (1) vanishes, i.e. if

$$\int_{-\infty}^{\infty} \Delta^\top \Phi \left(-\frac{d}{dt}, \frac{d}{dt} \right) w dt = 0$$

*ESAT, K.U. Leuven, B-3001 Leuven, Belgium, email: Jan.Willems@esat.kuleuven.ac.be.

This research is supported by the Belgian Federal Government under the DWTC program Interuniversity Attraction Poles, Phase V, 2002–2006, Dynamical Systems and Control: Computation, Identification and Modelling, by the KUL Concerted Research Action (GOA) MEFISTO–666, and by several grants en projects from IWT-Flanders and the Flemish Fund for Scientific Research.

for all $\Delta \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ of compact support. It is said to be *optimal* with respect to Φ , relative to variations Δ , if (1) is non-negative for all $\Delta \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ of compact support. Hence $w \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ is stationary if and only if

$$\Phi\left(-\frac{d}{dt}, \frac{d}{dt}\right)w = 0, \quad (2)$$

and optimal if and only if in addition

$$\int_{-\infty}^{\infty} Q_\Phi(\Delta) dt \geq 0 \quad (3)$$

for all $\Delta \in \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ of compact support. It is easy to prove (see [5]) that (3) holds if and only if the following frequency domain condition is satisfied:

$$\Phi(-i\omega, i\omega) \geq 0 \text{ for all } \omega \in \mathbb{R}. \quad (4)$$

Denote by \mathcal{L}^w the set of linear time-invariant differential systems in w variables, i.e. $\mathcal{B} \in \mathcal{L}^w$ means that $\mathcal{B} \subseteq \mathcal{C}^\infty(\mathbb{R}, \mathbb{R}^w)$ and that there exists a polynomial matrix $R \in \mathbb{R}^{\bullet \times w}[\xi]$ such that

$$R\left(\frac{d}{dt}\right)w = 0 \quad (5)$$

has \mathcal{B} as its \mathcal{C}^∞ solutions. Note that, while R specifies \mathcal{B} , the converse is not true (see [3]). The open problem is to

Characterize the behaviors $\mathcal{B} \in \mathcal{L}^w$ that are stationary or optimal.

In other words, under what conditions on $\mathcal{B} \in \mathcal{L}^w$ does there exist $\Phi = \Phi^* \in \mathbb{R}^{w \times w}[\zeta, \eta]$ such that $\mathcal{B} = \ker\left(\Phi\left(-\frac{d}{dt}, \frac{d}{dt}\right)\right)$? We are looking for conditions on \mathcal{B} directly, more than on representations of \mathcal{B} . This open problem is, of course, an high-order analogue of a well-studied problem in the calculus of variations and classical mechanics. The ideas and results from [4] are very relevant and partly solve the problem stated above.

It is straightforward to settle the case $w = 1$. In this case \mathcal{B} is stationary if and only if either $\mathcal{B} = \mathcal{C}^\infty(\mathbb{R}, \mathbb{R})$, or \mathcal{B} is a finite dimensional subset of $\mathcal{C}^\infty(\mathbb{R}, \mathbb{R})$ (i) of even dimension and (ii) time-reversible (in the sense that $t \in \mathbb{R} \mapsto w(t) \in \mathbb{R}$ belongs to \mathcal{B} if and only if $t \in \mathbb{R} \mapsto w(-t) \in \mathbb{R}$ belongs to \mathcal{B}). It is optimal if and only if in the finite dimensional case the following additional condition on the oscillatory solutions holds: (iii) whenever $t \in \mathbb{R} \mapsto t^k \sin \omega t$ belongs to \mathcal{B} for some even integer k and some $\omega \in \mathbb{R}$, then also $t \in \mathbb{R} \mapsto t^{k+1} \sin \omega t$ belongs to \mathcal{B} .

References

- [1] R.E. Kalman, *When is a linear control system optimal?*, Transactions of the ASME, Journal of Basic Engineering, Series D, **86** (1964), 81–90.
- [2] J.C. Willems, *Paradigms and puzzles in the theory of dynamical systems*, IEEE Transactions on Automatic Control, **36** (1991), 259–294.
- [3] J.W. Polderman and J.C. Willems, *Introduction to Mathematical Systems Theory: A Behavioral Approach*, Springer-Verlag, New York, 1998.
- [4] P. Rapisarda and H.L. Trentelman, *Linear Hamiltonian behaviors*, SIAM Journal on Control and Optimization, **43** (2004), 769–791.
- [5] J.C. Willems and H.L. Trentelman, *On quadratic differential forms*, SIAM Journal on Control and Optimization, **36** (1998), 1703–1749.