

Nonparametric regression estimation

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Regression function

Y real valued

X observation vector

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Regression problem

$$\min_f \mathbf{E}\{(Y - f(X))^2\}$$

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$$m(x) = \mathbf{E}\{Y | X = x\}$$

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For each function f , one has

$$\mathbf{E}\{(f(X) - Y)^2\} = \mathbf{E}\{\mathbf{E}\{(f(X) - Y)^2 | X\}\}$$

and

$$\mathbf{E}\{(f(X) - Y)^2 | X\} = \mathbf{E}\{(f(X) - m(X) + m(X) - Y)^2 | X\}$$

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Data: $D_n = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$

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$$m_n(x) = \frac{\frac{1}{n} \sum_{i=1}^n Y_i I_{\{X_i=x\}}}{\frac{1}{n} \sum_{i=1}^n I_{\{X_i=x\}}}$$

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a.s.

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Bandwidth $h = h_n$

h_n should be "small"

nh_n^d should be "large"

Error decomposition

$$\bar{m}_n(x) = \frac{\sum_{i=1}^n m(X_i) I_{\{\|X_i - x\| \leq h\}}}{\sum_{i=1}^n I_{\{\|X_i - x\| \leq h\}}}$$

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$$\begin{aligned} m_n(x) - m(x) &= m_n(x) - \bar{m}_n(x) + \bar{m}_n(x) - m(x) \\ &= \text{variation} + \text{bias} \end{aligned}$$

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Variation

$$m_n(x) - \bar{m}_n(x) = \frac{\sum_{i=1}^n (Y_i - m(X_i)) I_{\{\|X_i - x\| \leq h\}}}{\sum_{i=1}^n I_{\{\|X_i - x\| \leq h\}}}$$

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Bias

$$\bar{m}_n(x) - m(x) \approx \frac{\sum_{i=1}^n (m(X_i) - m(x)) I_{\{\|X_i - x\| \leq h\}}}{\sum_{i=1}^n I_{\{\|X_i - x\| \leq h\}}}$$

Error analysis: variation

$$\mathbf{E} \left\{ \left(\frac{\sum_{i=1}^n (Y_i - m(X_i)) I_{\{\|X_i - x\| \leq h\}}}{\sum_{i=1}^n I_{\{\|X_i - x\| \leq h\}}} \right)^2 \right\}$$

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For $i \neq j$,

$$\begin{aligned} & \mathbf{E} \left\{ (Y_i - m(X_i))(Y_j - m(X_j)) I_{\{\|X_i - x\| \leq h, \|X_j - x\| \leq h\}} \mid X_1, \dots, X_n, Y_i \right\} \\ = & (Y_i - m(X_i)) \mathbf{E} \{ Y_j - m(X_j) \mid X_1, \dots, X_n, Y_i \} I_{\{\|X_i - x\| \leq h, \|X_j - x\| \leq h\}} \\ = & 0 \end{aligned}$$

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if $nh_n^d \rightarrow \infty$.

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$$|m(x) - m(z)| \leq C\|x - z\|$$

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if $h = h_n \rightarrow 0$.

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- $m(x)$ is smooth
- X has a density
- Y is bounded

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Nonparametric features:

- construction of the estimate
- consistency

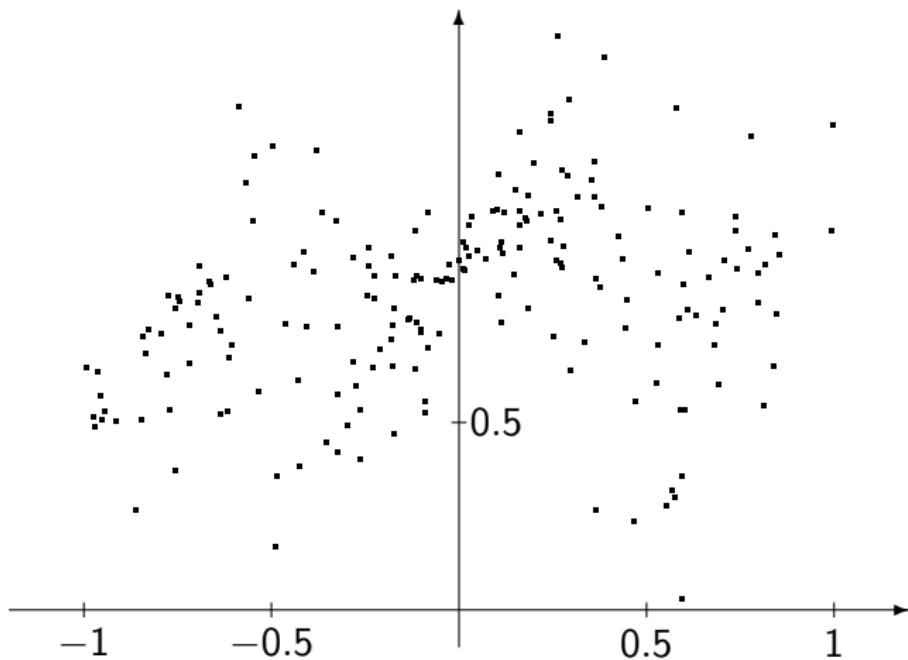
Definition

The estimator m_n is called **weakly universally consistent** if

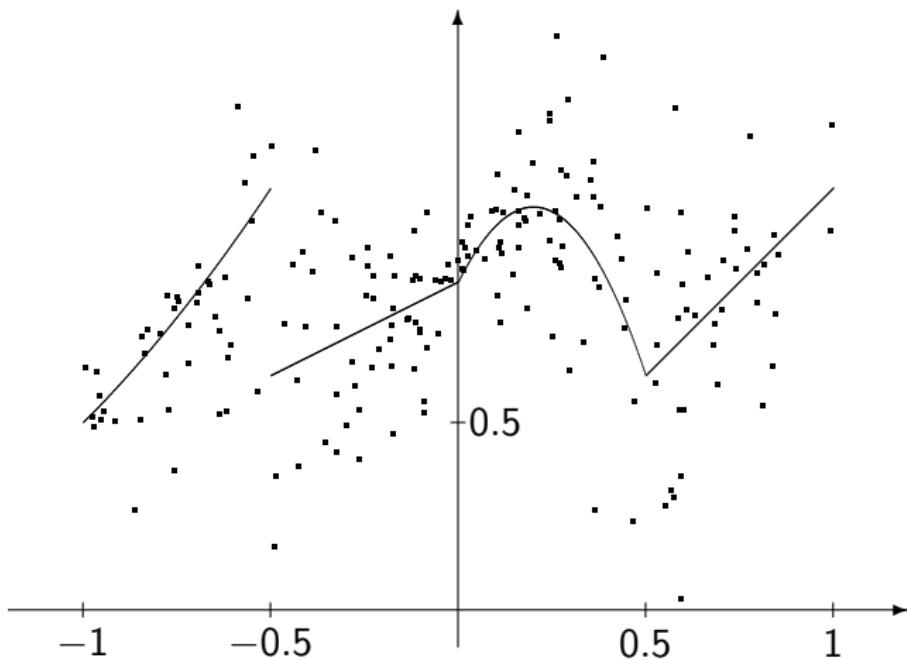
$$\mathbf{E} \{(m(X) - m_n(X))^2\} \rightarrow 0$$

for all distributions of (X, Y) with $\mathbf{E} Y^2 < \infty$.

Simulated data points.



Data points and regression function.



Local averaging estimates

Stone (1977)

$$m_n(x) = \sum_{i=1}^n W_{ni}(x; X_1, \dots, X_n) Y_i.$$

k -nearest neighbor estimate

W_{ni} is $1/k$ if X_i is one of the k nearest neighbors of x among X_1, \dots, X_n , and W_{ni} is 0 otherwise.

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nearest neighbor permutation: fix x

$$(X_1^{(x)}, Y_1^{(x)}), \dots, (X_n^{(x)}, Y_n^{(x)})$$

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such that $\|X_1^{(x)} - x\| \leq \|X_2^{(x)} - x\| \leq \dots \leq \|X_n^{(x)} - x\|$

k -nearest neighbor estimate

W_{ni} is $1/k$ if X_i is one of the k nearest neighbors of x among X_1, \dots, X_n , and W_{ni} is 0 otherwise. Formally

$$(X_1, Y_1), \dots, (X_n, Y_n)$$

nearest neighbor permutation: fix x

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Theorem

If $k_n \rightarrow \infty$, $k_n/n \rightarrow 0$ then the k -nearest neighbor estimate is weakly universally consistent.



Nearest neighbor estimate

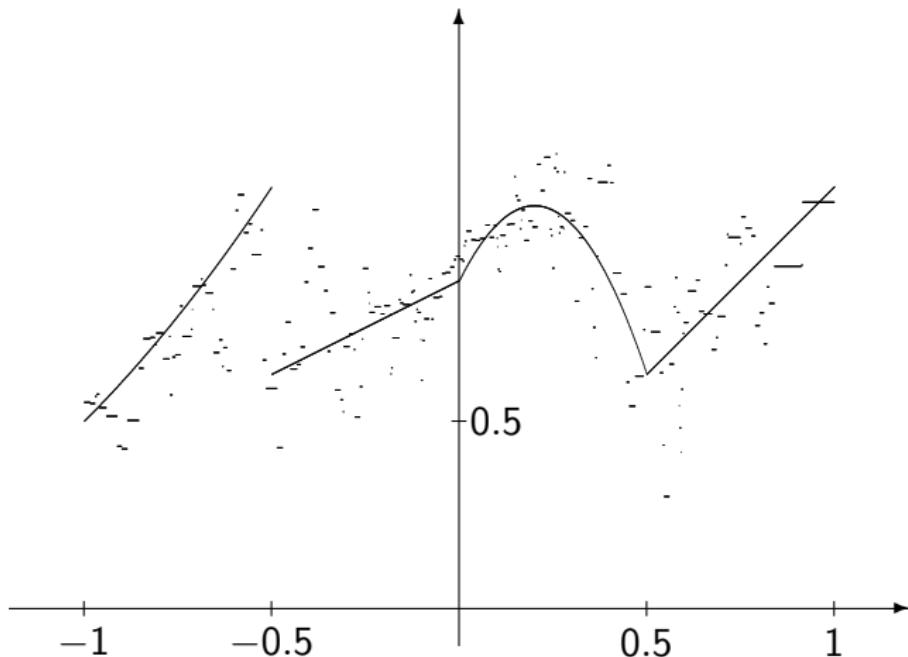


Figure: Undersmoothing: $k_n = 3$, L_2 error = 0.011703.

Nearest neighbor estimate

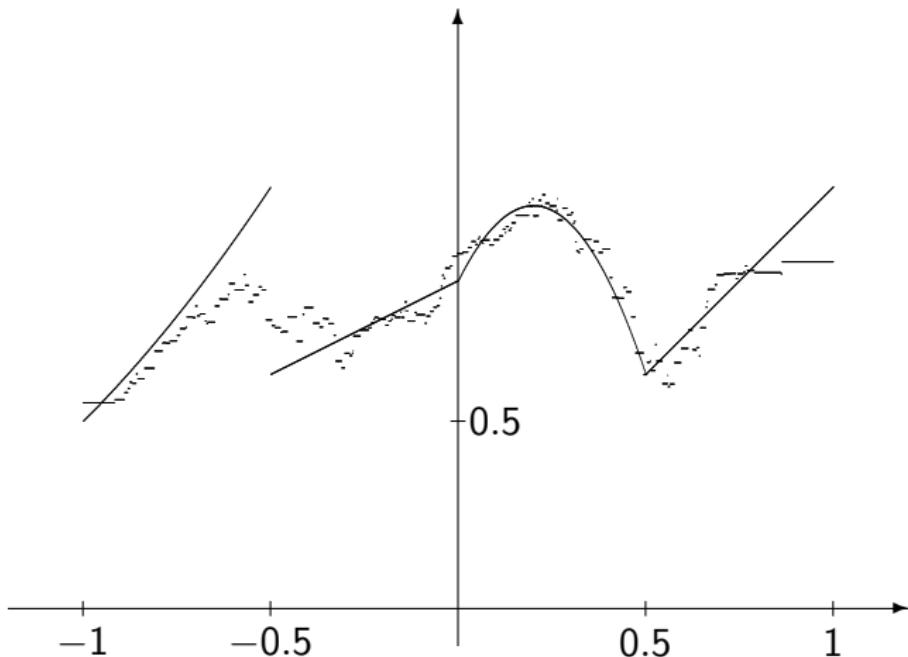


Figure: Good choice: $k_n = 12$, L_2 error = 0.004247.

Nearest neighbor estimate

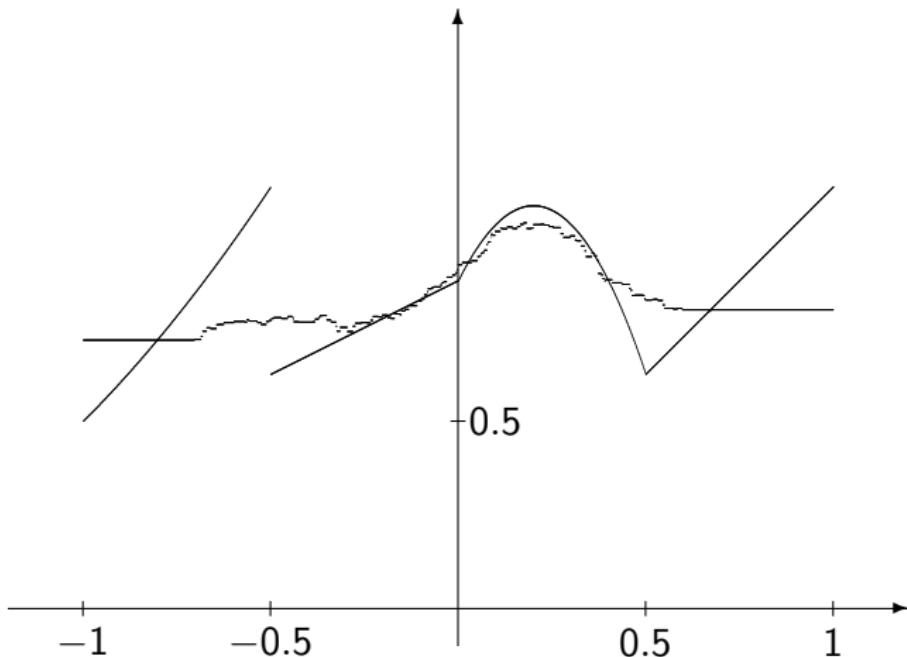


Figure: Oversmoothing: $k_n = 50$, L_2 error = 0.009931.

Partitioning estimate

Partition $\mathcal{P}_n = \{A_{n,1}, A_{n,2} \dots\}$

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Example: $A_{n,j}$ are cubes with volume h_n^d

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Example: $A_{n,j}$ are cubes with volume h_n^d

Theorem

For cubic partition, if

$$\lim_{n \rightarrow \infty} h_n = 0$$

and

$$\lim_{n \rightarrow \infty} nh_n^d \rightarrow \infty$$

then the partitioning estimate is weakly universally consistent.

Partitioning estimate

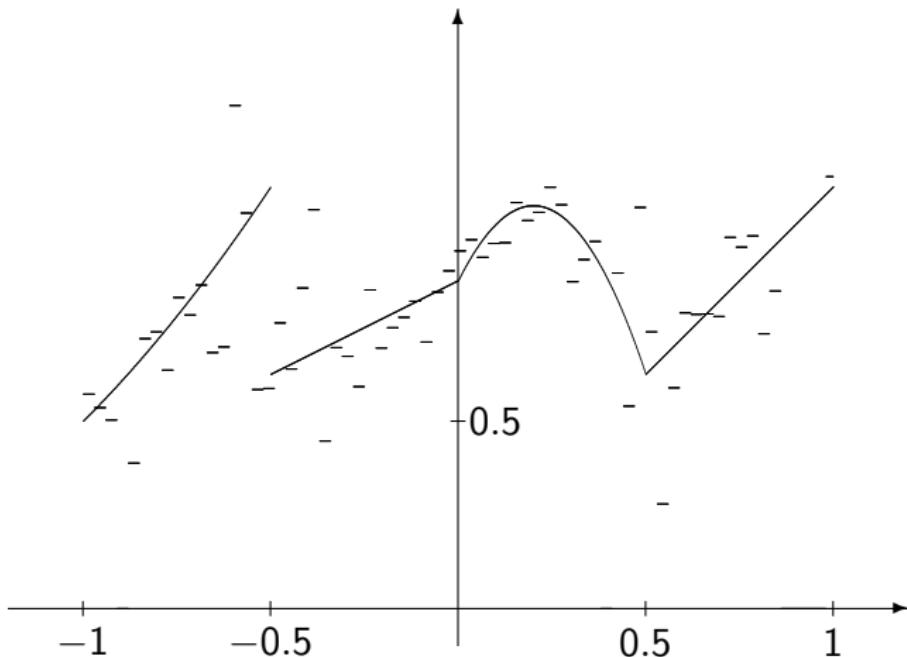


Figure: Undersmoothing: $h = 0.03$, L_2 error = 0.062433.

Partitioning estimate

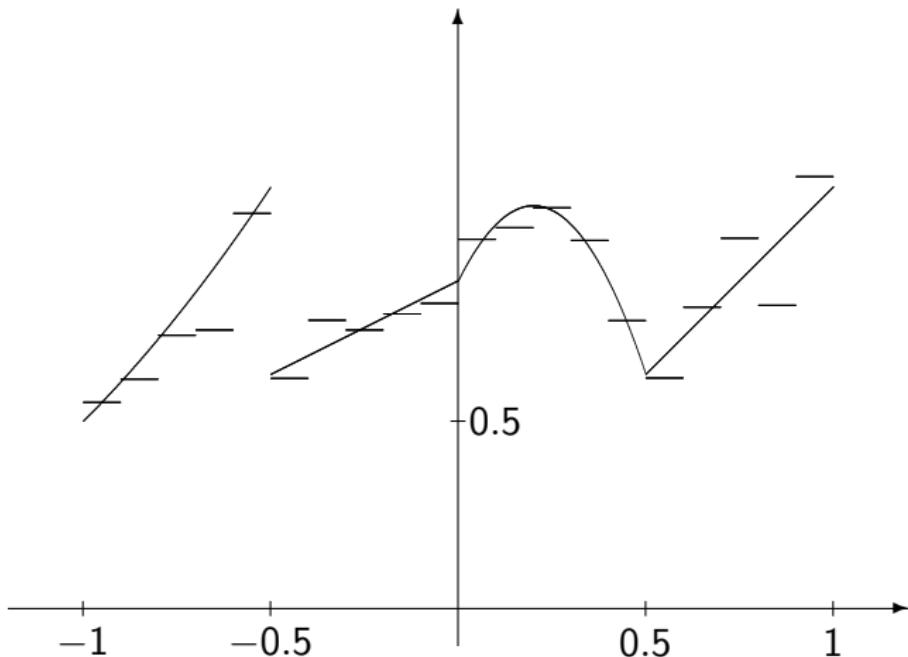


Figure: Good choice: $h = 0.1$, L_2 error = 0.003642.

Partitioning estimate

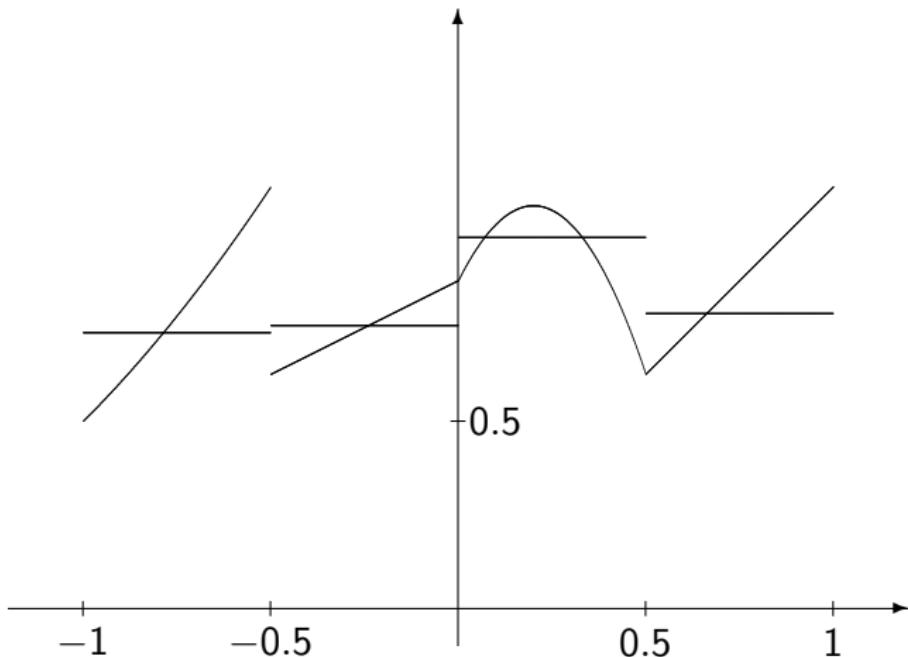


Figure: Oversmoothing: $h = 0.5$, L_2 error = 0.013208.

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Kernel function $K(x) \geq 0$

Bandwidth $h_n > 0$

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Theorem

If $h_n \rightarrow 0$, $nh_n^d \rightarrow \infty$ then under some conditions on K the kernel estimate is weakly universally consistent.

Kernel estimate

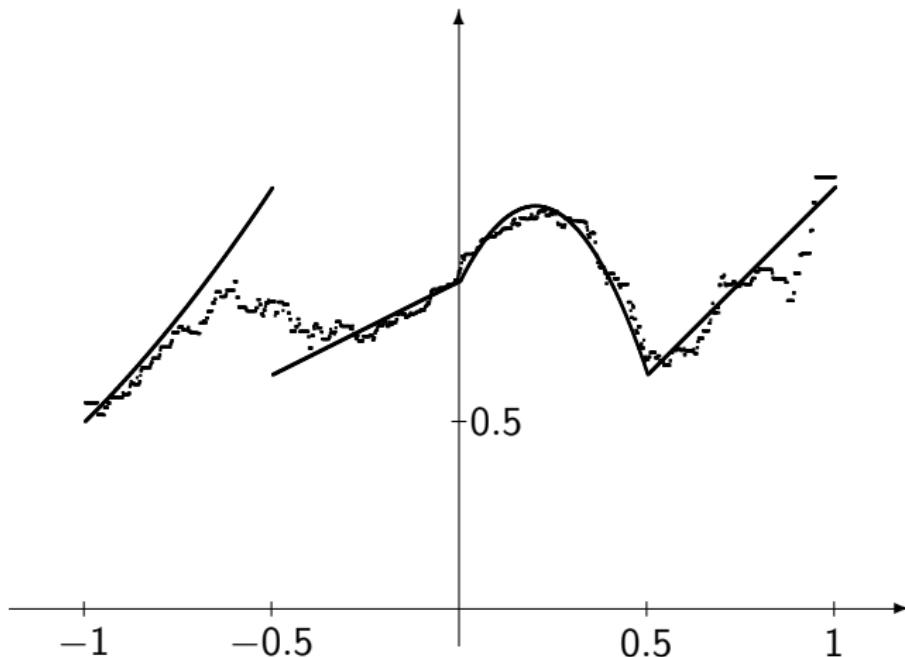


Figure: Kernel estimate for the naive kernel: $h = 0.1$, L_2 error = 0.004066.

Least squares estimates

Least squares estimates

Regression problem

$$\min_f \mathbf{E}\{(Y - f(X))^2\}$$

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empirical L_2 error

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the class \mathcal{F}_n grows slowly as n grows

Least squares estimates

Least squares estimates

Examples for \mathcal{F}_n :

- polynomials
- splines
- neural networks
- radial basis functions

Springer Series in Statistics

László Györfi Michael Kohler
Adam Krzyżak Harro Walk

A Distribution-Free Theory of Nonparametric Regression



Springer

Prediction of time series: squared loss

László (Laci) Györfi¹

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August 27, 2012

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Prediction for squared loss

Y_i real valued

X_i vector valued

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At time instant i the predictor is asked to guess Y_i

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After n time instant the empirical squared error

$$L_n(g) = \frac{1}{n} \sum_{i=1}^n (g_i(X_1^i, Y_1^{i-1}) - Y_i)^2.$$

Dependent data: time series

The data $D_n = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$ are **dependent**

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The fundamental limit: for any predictor g

$$\liminf_{n \rightarrow \infty} L_n(g) \geq \lim_{n \rightarrow \infty} L_n(g^*) = L^* \quad \text{almost surely},$$

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where

$$L^* = \mathbf{E}\{(Y_0 - \mathbf{E}\{Y_0 | X_{-\infty}^0, Y_{-\infty}^{-1}\})^2\}$$

is the minimal mean squared error of any prediction for the value of Y_0 based on the infinite past $X_{-\infty}^0, Y_{-\infty}^{-1}$.

Universal consistency

there are universally consistent prediction sequence g_n :

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n (g_i(X_1^i, Y_1^{i-1}) - Y_i)^2 = L^*$$

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Such prediction sequence is called **universally consistent**.

Elementary experts via local averaging

window kernel based elementary predictor (expert): $h^{(k,\ell)}$,
 $k, \ell = 1, 2, \dots$

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location of the matches

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location of the matches

$$J_n^{(k,\ell)} = \left\{ k < i < n : \|x_{i-k}^i - x_{n-k}^n\| \leq r_{k,\ell}, \|y_{i-k}^{i-1} - y_{n-k}^{n-1}\| \leq r'_{k,\ell} \right\}$$

Then the local averaging prediction of the expert (k, ℓ) is the average of y_i 's if $i \in J_n^{(k, \ell)}$:

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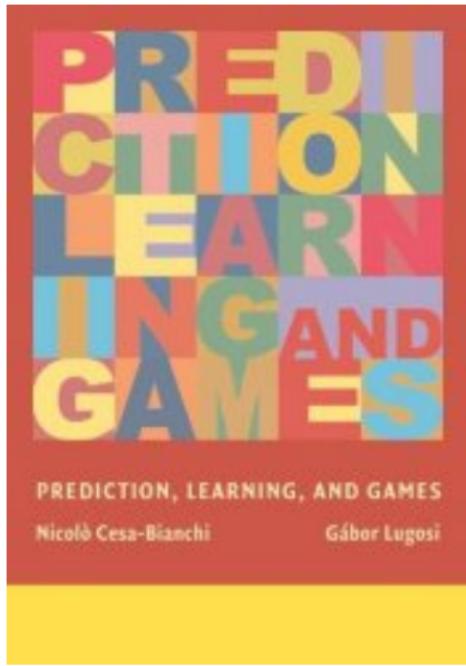
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for large radius, the bias is large and, for small radius, the variance
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The problem is how to choose k , $r_{k, \ell} > 0$ and $r'_{k, \ell} > 0$ in a data
dependent way.



Combination of experts: bounded Y

Machine learning: exponential weighting

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$|Y| \leq B$, and B is known.

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Then the combined prediction

$$g_t(x_1^t, y_1^{t-1}) = \sum_{k,\ell=1}^{\infty} p_{t,k,\ell} h^{(k,\ell)}(x_1^t, y_1^{t-1}) .$$

Theorem. (Györfi, Lugosi (2001)) If $|Y_0| \leq B$, then the combined predictor g is universally consistent.

Expert Lemma

Let $\tilde{h}_1, \tilde{h}_2, \dots$ be a sequence of prediction strategies (experts), and let $\{q_k\}$ be a probability distribution on the set of positive integers.

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If the prediction strategy \tilde{g} is defined by

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then for every $n \geq 1$,

$$L_n(\tilde{g}) \leq \inf_k \left(L_n(\tilde{h}_k) - \frac{c \ln q_k}{n} \right).$$

Proof

Introduce

$$W_1 = 1$$

and

$$W_t = \sum_{k=1}^{\infty} w_{t,k}$$

for $t > 1$.

Proof

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$$W_t = \sum_{k=1}^{\infty} w_{t,k}$$

for $t > 1$. Note that

$$W_{t+1} = \sum_{k=1}^{\infty} w_{t,k} e^{-\left(y_t - \tilde{h}_k(x_1^t, y_1^{t-1})\right)^2/c} = W_t \sum_{k=1}^{\infty} v_{t,k} e^{-\left(y_t - \tilde{h}_k(x_1^t, y_1^{t-1})\right)^2/c},$$

so that

$$-c \ln \frac{W_{t+1}}{W_t} = -c \ln \left(\sum_{k=1}^{\infty} v_{t,k} e^{-\left(y_t - \tilde{h}_k(x_1^t, y_1^{t-1})\right)^2/c} \right).$$

so that

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Introduce the function

$$F_t(z) = e^{-(y_t - z)^2/c}$$

so that

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Because of $c \geq 8B^2$, the function F_t is concave on $[-B, B]$, therefore Jensen's inequality implies that

$$\left[\sum_{k=1}^{\infty} v_{t,k} \left(y_t - \tilde{h}_k(x_1^t, y_1^{t-1}) \right) \right]^2 \leq -c \ln \frac{W_{t+1}}{W_t}$$

Thus,

$$nL_n(\tilde{g}) = \sum_{t=1}^n (y_t - \tilde{g}(x_1^t, y_1^{t-1}))^2$$

Thus,

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Thus,

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Thus,

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and therefore

$$\begin{aligned} nL_n(\tilde{g}) &\leq -c \ln \left(\sum_{k=1}^{\infty} w_{n+1,k} \right) \\ &= -c \ln \left(\sum_{k=1}^{\infty} q_k e^{-nL_n(\tilde{h}_k)/c} \right) \end{aligned}$$

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Sketch of the proof of the Theorem

Because of the fundamental limit

$$\liminf_{n \rightarrow \infty} L_n(g) \geq \lim_{n \rightarrow \infty} L_n(g^*) = L^* \quad \text{a.s.}$$

Sketch of the proof of the Theorem

Because of the fundamental limit

$$\liminf_{n \rightarrow \infty} L_n(g) \geq \lim_{n \rightarrow \infty} L_n(g^*) = L^* \quad \text{a.s.}$$

it is enough to show that

$$\limsup_{n \rightarrow \infty} L_n(g) \leq L^* \quad \text{a.s.}$$

By the Expert Lemma

$$L_n(g) \leq \inf_{k,\ell} \left(L_n(h^{(k,\ell)}) - \frac{c \ln q_{k,\ell}}{n} \right),$$

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Pattern recognition

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Decision problem

Y $\{1, 2, \dots, M\}$ valued
 X feature vector

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Classifier

$$g : \mathbb{R}^d \rightarrow \{1, 2, \dots M\}.$$

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Probability of error:

$$P(g(X) \neq Y).$$

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$$g : \mathbb{R}^d \rightarrow \{1, 2, \dots, M\}.$$

Probability of error:

$$P(g(X) \neq Y).$$

Problem: find

$$\min_g P(g(X) \neq Y).$$

Bayes decision

a posteriori probability

$$P_i(x) = \mathbf{P}\{Y = i | X = x\}.$$

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L^* Bayes error

Lemma

For any decision g ,

$$L^* := \mathbf{P}\{g^*(X) \neq Y\} \leq \mathbf{P}\{g(X) \neq Y\}.$$

$$\mathbf{P}\{g(X) \neq Y\} = \mathbf{E}\{\mathbf{P}\{g(X) \neq Y | X\}\}$$

and

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Proof

$$\mathbf{P}\{g(X) \neq Y\} = \mathbf{E}\{\mathbf{P}\{g(X) \neq Y | X\}\}$$

and

$$\mathbf{P}\{g(X) \neq Y | X\} = 1 - \mathbf{P}\{g(X) = Y | X\}$$

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$$\begin{aligned}\mathbf{P}\{g(X) \neq Y | X\} &= 1 - \mathbf{P}\{g(X) = Y | X\} \\ &= 1 - \sum_{j=1}^M \mathbf{P}\{g(X) = j, Y = j | X\}\end{aligned}$$

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Thus

$$\mathbf{P}\{g(X) \neq Y \mid X\}$$

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Thus

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Plug-in rule

$\tilde{P}_i(x)$ approximations of $P_i(x)$

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Lemma

$$\mathbf{P}\{g(X) \neq Y\} - L^* \leq \sum_{j=1}^M \mathbf{E}\{|P_j(X) - \tilde{P}_j(X)|\}.$$

Proof

$$\mathbf{P}\{g(X) \neq Y \mid X\} = 1 - \sum_{j=1}^M I_{\{g(X)=j\}} P_j(X)$$

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$$\mathbf{P}\{g(X) \neq Y \mid X\} = 1 - \sum_{j=1}^M I_{\{g(X)=j\}} P_j(X) = 1 - P_{g(X)}(X)$$

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Thus

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$$\mathbf{P}\{g(X) \neq Y | X\} = 1 - \sum_{j=1}^M I_{\{g(X)=j\}} P_j(X) = 1 - P_{g(X)}(X)$$

Thus

$$\mathbf{P}\{g(X) \neq Y | X\} - \mathbf{P}\{g^*(X) \neq Y | X\} = P_{g^*(X)}(X) - P_{g(X)}(X)$$

If $g^*(X) = g(X)$ then

$$\mathbf{P}\{g(X) \neq Y | X\} - \mathbf{P}\{g^*(X) \neq Y | X\} = 0$$

If $g^*(X) \neq g(X)$ then

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If $g^*(X) \neq g(X)$ then

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Universal consistency

Data: $(X_1, Y_1), \dots, (X_n, Y_n)$

Data: $(X_1, Y_1), \dots, (X_n, Y_n)$

$$g_n(x) = g_n((X_1, Y_1), \dots, (X_n, Y_n), x).$$

Definition

The classifier g_n is called **weakly universally consistent** if

$$P(g_n(X) \neq Y) \rightarrow L^*$$

for all distributions of (X, Y) .

Local majority voting

the a posteriori probabilities

$$P_i(x) = \mathbf{P}\{Y = i | X = x\} = \mathbf{E}\{I_{\{Y=i\}} | X = x\}$$

are regression functions,

Local majority voting

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plug-in rule: local majority voting

$$g_n(x) = \arg \max_j \sum_{i=1}^n \tilde{P}_{n,j}(x) = \arg \max_j \sum_{i=1}^n W_{n,i}(x) I_{\{Y_i=j\}},$$

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$$\begin{aligned} \mathbf{P}\{g(X) \neq Y\} - L^* &\leq \sum_{j=1}^M \mathbf{E}\{|P_j(X) - \tilde{P}_{n,j}(X)|\} \\ &\leq \sum_{j=1}^M \sqrt{\mathbf{E}\{|P_j(X) - \tilde{P}_{n,j}(X)|^2\}}. \end{aligned}$$

k -nearest neighbor rule

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Kernel rule rule:

$$g_n(x) = \arg \max_j \sum_{i=1}^n K\left(\frac{X_i - x}{h}\right) I_{\{Y_i=j\}}.$$

Local majority voting

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Theorem

The k -NN rule and the partitioning rule and the kernel rule are strongly universally consistent.



Empirical error minimization

empirical error

$$\frac{1}{n} \sum_{j=1}^n I_{\{g(X_j) \neq Y_j\}}$$

Empirical error minimization

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Examples for \mathcal{G}_n :

- polynomial classifiers
- tree classifiers
- neural networks classifiers
- radial basis functions classifiers

Luc Devroye
László Györfi
Gábor Lugosi

A Probabilistic Theory of Pattern Recognition

Applications of Mathematics
Stochastic Modelling and Applied Probability



Springer

Prediction of time series: 0 – 1 loss

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August 27, 2012

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$0 - 1$ loss

Y_i takes values in the finite set $\{0, 1\}$.

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After n round the empirical 0 – 1 error for X_1^n, Y_1^n is

$$R_n(f) = \frac{1}{n} \sum_{i=1}^n I_{\{f(X_1^i, Y_1^{i-1}) \neq Y_i\}},$$

i.e., the loss is the 0 – 1 loss, and $R_n(f)$ is the relative frequency of errors.

Dependent data: time series

data $D_n = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$ form a stationary and ergodic process

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Fundamental limit: for any classification strategy f and stationary ergodic process $\{(X_n, Y_n)\}_{n=-\infty}^\infty$,

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where

$$R^* = \mathbf{E} \left\{ \min \left(\mathbf{P}\{Y_0 = 1 | X_{-\infty}^0, Y_{-\infty}^{-1}\}, \mathbf{P}\{Y_0 = 0 | X_{-\infty}^0, Y_{-\infty}^{-1}\} \right) \right\}.$$

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Such classifier sequence is called **universally consistent**.

Theorem

Let $g_t(X_1^t, Y_1^{t-1})$ be a universally consistent prediction scheme, for bounded Y , estimating the conditional probability

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Then f_t is a universally consistent classifier (Györfi, Lugosi (2001)).

Martingale difference sequences

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Definition

there are two sequences of random variables:

$$\{Z_n\} \quad \{X_n\}$$

- Z_n is a function of X_1, \dots, X_n ,
- $\mathbf{E}\{Z_n | X_1, \dots, X_{n-1}\} = 0$ almost surely.

Then $\{Z_n\}$ is called martingale difference sequence with respect to $\{X_n\}$.

A strong law of large numbers

Chow Theorem:

A strong law of large numbers

Chow Theorem: If $\{Z_n\}$ is a martingale difference sequence with respect to $\{X_n\}$ and

$$\sum_{n=1}^{\infty} \frac{\mathbf{E}\{Z_n^2\}}{n^2} < \infty$$

then

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{i=1}^n Z_i = 0 \text{ a.s.}$$

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if, for example, $\mathbf{E}\{Z_i^2\}$ is a bounded sequence.

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$$\begin{aligned} |\bar{R}_n(f^*) - \bar{R}_n(f)| &\leq \frac{1}{n} \sum_{i=1}^n |g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i \mid X_{-\infty}^i, Y_{-\infty}^{i-1}\}| \\ &\leq \sqrt{\frac{1}{n} \sum_{i=1}^n |g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i \mid X_{-\infty}^i, Y_{-\infty}^{i-1}\}|^2} \end{aligned}$$

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Corollary

Let $\{g_n\}$ be a sequence of universally consistent predictors for the class of stationary, ergodic processes with $|Y| < B$,

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a.s.

Decomposition

$$\begin{aligned} & (g_i(X_1^i, Y_1^{i-1}) - Y_i)^2 \\ = & (g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\})^2 \\ & + 2(g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\})(\mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\} - Y_i) \\ & + (\mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\} - Y_i)^2 \end{aligned}$$

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Thus

$$\begin{aligned}
 & (g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\})^2 \\
 = & (g_i(X_1^i, Y_1^{i-1}) - Y_i)^2 \\
 & - 2(g_i(X_1^i, Y_1^{i-1}) - \mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\})(\mathbf{E}\{Y_i | X_{-\infty}^i, Y_{-\infty}^{i-1}\} - Y_i) \\
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László Györfi
György Ottucsák
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MACHINE LEARNING FOR FINANCIAL ENGINEERING