

# Symmetric tensor decomposition

J. Brachat GALAAD, INRIA, Sophia Antipolis Joint work with P. Comon, B. Mourrain, E. Tsigaridas

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We present an algorithm for decomposing a symmetric tensor, of dimension  $n$  and order  $d$ , as a sum of rank-1 symmetric tensors, extending the algorithm of Sylvester devised in 1886 for binary forms.

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$$v = \sum_{i_1 < \dots < i_d} A_{i_1, \dots, i_d} e_{i_1} \dots e_{i_d} \in \wedge^d E$$

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## **Motivations :**

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- Earlier in the 1970s tensors have been used in Chemometrics and Psychometrics.
- Another important application field is Data Analysis, for instance, Independent Component Analysis, originally introduced for symmetric tensors whose rank did not exceed dimension.

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- Current numerical algorithms are suboptimal (they do not use symmetries, they minimize different successive criteria sequentially or are iterative and do not guarantee a global convergence). In addition they often require the rank to be lower than the generic one.
- Among these popular methods, we refer to “PARAFAC” techniques, extensively applied to ill-posed problems.

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- We describe a new algorithm that decomposes a symmetric tensor of arbitrary order and dimension into a sum of rank-one terms. The method is inspired by Sylvester's theorem and extends its principle to larger dimensions.



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- We give necessary and sufficient condition for the existence of a decomposition of rank  $r$ , based on rank conditions of Hankel operators or commutation properties.
- This algorithm is not restricted to strictly sub-generic ranks and fully exploits the symmetries.

# Binary case

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### Theorem (Sylvester, 1886)

A binary quantic  $p(x_1, x_2) = \sum_{i=0}^d \binom{d}{i} c_i x_1^i x_2^{d-i}$  can be written as a sum of  $d^{\text{th}}$  powers of  $r$  distinct linear forms in  $\mathbb{C}$  as:

$$p(x_1, x_2) = \sum_{j=1}^r \lambda_j (\alpha_j x_1 + \beta_j x_2)^d, \quad (1)$$

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if and only if (i) there exists a vector  $\mathbf{q} = (q_l)_{l=0}^r$ , such that

$$\begin{bmatrix} c_0 & c_1 & \cdots & c_r \\ \vdots & & & \vdots \\ c_{d-r} & \cdots & c_{d-1} & c_d \end{bmatrix} \mathbf{q} = \mathbf{0}. \quad (2)$$

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and (ii) the polynomial  $q(x_1, x_2) = \sum_{l=0}^r q_l x_1^l x_2^{r-l}$  admits  $r$  distinct roots, i.e. can be written as  $q(x_1, x_2) = \prod_{j=1}^r (\beta_j^* x_1 - \alpha_j^* x_2)$ .

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**Input** : Given a binary polynomial  $p(x_1, x_2)$  of degree  $d$  with coefficients  $a_i = \binom{d}{i} c_i$ ,  $0 \leq i \leq d$ , define the Hankel matrix  $H[r]$  of dimensions  $d - r + 1 \times r + 1$  with entries  $H[r]_{ij} = c_{i+j-2}$ :

$$H[r] = \begin{bmatrix} c_0 & c_1 & \cdots & c_r \\ \vdots & & & \vdots \\ c_{d-r} & \cdots & c_{d-1} & c_d \end{bmatrix}. \quad (3)$$

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**Output** : A decomposition of  $p$  as  $p(x_1, x_2) = \sum_{j=1}^r \lambda_j \mathbf{k}_j(\mathbf{x})^d$  with minimal  $r$ .



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$$\begin{bmatrix} \alpha_1^d & \dots & \alpha_r^d \\ \alpha_1^{d-1} \beta_1 & \dots & \alpha_r^{d-1} \beta_r \\ \alpha_1^{d-2} \beta_1^2 & \dots & \alpha_r^{d-1} \beta_r^2 \\ \vdots & \vdots & \vdots \\ \beta_1^d & \dots & \beta_r^d \end{bmatrix} \lambda = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_d \end{bmatrix}$$



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- 6 The decomposition is  $p(x_1, x_2) = \sum_{j=1}^r \lambda_j \mathbf{k}_j(\mathbf{x})^d$ , where  $\mathbf{k}_j(\mathbf{x}) = (\alpha_j \mathbf{x}_1 + \beta_j \mathbf{x}_2)$ .



# Reformulations

## 1) Polynomial decomposition:

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A symmetric tensor  $[a_{j_0, \dots, j_{n-1}}]$  of order  $d$  and dimension  $n$  can be associated to a homogeneous polynomial  $f(\mathbf{x}) \in \mathbf{S}_d$ :

$$f(\mathbf{x}) = \sum_{j_0 + j_1 + \dots + j_{n-1} = d} a_{j_0, j_1, \dots, j_{n-1}} x_0^{j_0} x_1^{j_1} \dots x_{n-1}^{j_{n-1}}. \quad (4)$$

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where  $\lambda_i \neq 0$ ,  $\mathbf{k}_i \neq \mathbf{0}$ , and  $r$  is the smallest possible.

This minimal  $r$  is called the **rank** of  $f$ .

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The closure of the  $r$ -dimensional linear space spanned by  $r$  points of the Veronese is called the  **$r-1$  secant** variety.

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Let  $f, g \in S_d$ , where  $f = \sum_{|\alpha|=d} f_\alpha x_0^{\alpha_0} \cdots x_{n-1}^{\alpha_{n-1}}$  and  $g = \sum_{|\alpha|=d} g_\alpha x_0^{\alpha_0} \cdots x_{n-1}^{\alpha_{n-1}}$ .

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Using this non-degenerate inner product, we can associate an element of  $S_d$  with an element  $S_d^*$ , through the following map:

$$\begin{aligned} \tau: S_d &\rightarrow S_d^* \\ f &\mapsto f^*, \end{aligned}$$

where the linear form  $f^*$  is defined as  $f^*: g \mapsto \langle f, g \rangle$ .



## Proposition

Let  $f = (a_0x_0 + \dots + a_{n-1}x_{n-1})^d \in S_d$ , then

$$f^*(g) = \langle f, g \rangle = g(a_0, \dots, a_{n-1}) = \mathbf{ev}_A(g)$$

with  $A = (a_0, \dots, a_{n-1}) \in \mathbb{K}^{n-1}$ ,  $g \in S_d$  and  $\mathbf{ev}_A$  is the *evaluation* in  $A$ .

The decomposition problem can be reformulated as follows:

*Given  $f^* \in S_d^*$ , find the minimal number of non-zero points  $\mathbf{k}_1, \dots, \mathbf{k}_r \in \mathbb{K}^n$  and non-zero scalars  $\lambda_1, \dots, \lambda_r \in \mathbb{K} - \{0\}$  such that*

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Note that by a generic change of variables, we can assume that all the coordinates  $\mathbf{k}_{i,0}$  are equal to 1.

# Hankel operators and quotient algebras

## Definition

Let  $R = \mathbb{K}[x_1, \dots, x_{n-1}]$  be the polynomial ring in  $n-1$  variables and  $\Lambda \in R^*$  be a linear form. We define the **Hankel operator**  $H_\Lambda$  from  $R$  to  $R^*$  as

$$H_\Lambda : R \rightarrow R^* \\ p \mapsto p \star \Lambda$$

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We denote by  $\mathbb{H}_\Lambda$  the matrix of  $H_\Lambda$  in the basis  $\{x^\alpha\}$  and  $\{\mathbf{d}^\alpha\}$  (where  $\{\mathbf{d}^\alpha\}$  is the dual basis of the monomial basis  $\{x^\alpha\}$ ). Thus

$$\mathbb{H}_\Lambda = (\Lambda(x^{\alpha+\beta}))_{\alpha,\beta}.$$

# Hankel operators and quotient algebras

## Proposition

*Let  $I_\Lambda$  be the kernel of  $H_\Lambda$ . Then,  $I_\Lambda$  is an ideal of  $R$ .*

# Hankel operators and quotient algebras

## Proposition

Let  $I_\Lambda$  be the kernel of  $H_\Lambda$ . Then,  $I_\Lambda$  is an ideal of  $R$ .

## Definition

Let  $\mathcal{A}_\Lambda := R/I_\Lambda$  be the quotient algebra of polynomials modulo the ideal  $I_\Lambda$ .

# Hankel operators and quotient algebras

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- Let  $a \in R$  be a polynomial. Let  $M_a$  be the multiplication by  $a$  in  $\mathcal{A}_\Lambda$ :

$$\begin{aligned} M_a & : \mathcal{A}_\Lambda \rightarrow \mathcal{A}_\Lambda \\ & b \mapsto ba. \end{aligned}$$



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- Let  $M_a^t$  be the be its transposed operator:

$$M_a^t : \mathcal{A}_\Lambda^* \rightarrow \mathcal{A}_\Lambda^* \\ \gamma \mapsto a \star \gamma.$$

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Note that, by definition, we have

$$H_{a \star \Lambda} = M_a^t \circ H_\Lambda$$

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- there exist  $p_i \in \mathbb{K}[\partial_1, \dots, \partial_n]$ , such that

$$\Lambda = \sum_{i=1}^d \mathbf{ev}_{\zeta_i} \circ p_i(\partial) \quad (6)$$

Moreover the multiplicity of  $\zeta_i$  is the dimension of the vector space spanned by the inverse system generated by  $\mathbf{ev}_{\zeta_i} \circ p_i(\partial)$ .

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- the eigenvalues of the operators  $M_a$  and  $M_a^t$ , are given by  $\{a(\zeta_1), \dots, a(\zeta_d)\}$ .
- the common eigenvectors of the operators  $(M_{x_i}^t)_{1 \leq i \leq n}$  are (up to scalar)  $\mathbf{ev}_{\zeta_i}$ .

# Hankel operators and quotient algebras

## Theorem

Let  $\Lambda \in R^*$ .  $\Lambda = \sum_{i=1}^r \lambda_i \mathbf{e} \mathbf{v}_{\zeta_i}$  with  $\lambda_i \neq 0$  and  $\zeta_i$  distinct points of  $\mathbb{K}^n$ , iff  $\text{rank} H_\Lambda = r$  and  $I_\Lambda$  is a *radical* ideal.



**The problem of decomposition can be reformulated as follows :**

Given  $f^* \in R_d^*$  find the smallest  $r$  such that there exists  $\Lambda \in R^*$  which extends  $f^*$  with  $H_\Lambda$  of rank  $r$  and  $I_\Lambda$  a radical ideal.

# Truncated Hankel operators

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We denote by  $\mathcal{H}_{\Lambda_{f^*}}^B(\mathbf{h})$  its matrix:

$$\mathcal{H}_{\Lambda_{f^*}}^B(\mathbf{h}) = (h_{\alpha+\beta})_{\alpha, \beta \in B}.$$

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If  $\mathcal{H}_{\Lambda_{f^*}}^B(\mathbf{h})$  is invertible in  $\mathbb{K}(\mathbf{h})$  (that is the rational polynomial functions in  $\mathbf{h}$ ), then we define the multiplication operators

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## Definition

Let  $B$  be a subset of monomials in  $R$ . We say that  $B$  is **connected to 1** if:

- $1 \in B$ ,
- $\forall m \neq 1 \in B$  there exists  $i \in [1, n]$  and  $m' \in B$  such that  $m = x_i m'$ .

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-Let  $\Lambda_{f^*}(\mathbf{h})$  be the linear form of  $\langle B \cdot B^+ \rangle^*$  defined by  $\Lambda_{f^*}(\mathbf{h})(\mathbf{x}^\alpha) = f^*(\mathbf{x}^\alpha)$  if  $|\alpha|$  is at most  $d$  and  $h_\alpha \in \mathbb{K}$  otherwise.

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Then  $\Lambda_{f^*}(\mathbf{h})$  admits an extension  $\tilde{\Lambda} \in R^*$  such that  $H_{\tilde{\Lambda}}$  is of rank  $r$  with  $B$  a basis of  $A_{\tilde{\Lambda}}$  iff

$$\mathcal{M}_i^B(\mathbf{h}) \circ \mathcal{M}_j^B(\mathbf{h}) - \mathcal{M}_j^B(\mathbf{h}) \circ \mathcal{M}_i^B(\mathbf{h}) = 0 \quad (1 \leq i < j \leq n) \quad (7)$$

and  $\det(\mathcal{H}_{\tilde{\Lambda}^*}^B)(\mathbf{h}) \neq 0$ . Moreover, such a  $\tilde{\Lambda}$  is unique.

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**until** the eigenvalues are simple.

- Solve the linear system in  $(c_j)_{j=1, \dots, k}$ :  $\Lambda = \sum_{j=1}^r c_j \mathbf{e} \mathbf{v}_{\zeta_j}$  where  $\zeta_j \in \mathbb{K}^n$  are the eigenvectors found in step 4.

## Example

Assume that a tensor of dimension three and order 5 corresponds to the following homogeneous polynomial:

$$\begin{aligned} f = & -1549440 x_0 x_1 x_2^3 + 2417040 x_0 x_1^2 x_2^2 + 166320 x_0^2 x_1 x_2^2 - 829440 x_0 x_1^3 x_2 - \\ & 5760 x_0^3 x_1 x_2 - 222480 x_0^2 x_1^2 x_2 + 38 x_0^5 - 497664 x_1^5 - 1107804 x_2^5 - 120 x_0^4 x_1 + \\ & 180 x_0^4 x_2 + 12720 x_0^3 x_1^2 + 8220 x_0^3 x_2^2 - 34560 x_0^2 x_1^3 - 59160 x_0^2 x_2^3 + \\ & 831840 x_0 x_1^4 + 442590 x_0 x_2^4 - 5591520 x_1^4 x_2 + 7983360 x_1^3 x_2^2 - \\ & 9653040 x_1^2 x_2^3 + 5116680 x_1 x_2^4. \end{aligned}$$

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The **minimum decomposition** of the polynomial as a sum of powers of linear forms is

$$(x_0 + 2x_1 + 3x_2)^5 + (x_0 - 2x_1 + 3x_2)^5 + \frac{1}{3}(x_0 - 12x_1 - 3x_2)^5 + \frac{1}{5}(x_0 + 12x_1 - 13x_2)^5,$$

that is, the corresponding tensor is of rank 4.

## Example

The whole matrix is  $21 \times 21$ . We show only the  $10 \times 10$  principal minor.

	1	$x_1$	$x_2$	$x_1^2$	$x_1 x_2$	$x_2^2$	$x_1^3$	$x_1^2 x_2$	$x_1 x_2^2$	$x_2^3$
1	38	-24	36	1272	-288	822	-3456	-7416	5544	-5916
$x_1$	-24	1272	-288	-3456	-7416	5544	166368	-41472	80568	-77472
$x_2$	36	-288	822	-7416	5544	-5916	-41472	80568	-77472	88518
$x_1^2$	1272	-3456	-7416	166368	-41472	80568	-497664	-1118304	798336	-965304
$x_1 x_2$	-288	-7416	5544	-41472	80568	-77472	-1118304	798336	-965304	1023336
$x_2^2$	822	5544	-5916	80568	-77472	88518	798336	-965304	1023336	-1107804
$x_1^3$	-3456	166368	-41472	-497664	-1118304	798336	$h_{6,0,0}$	$h_{5,1,0}$	$h_{4,2,0}$	$h_{3,3,0}$
$x_1^2 x_2$	-7416	-41472	80568	-1118304	798336	-965304	$h_{5,1,0}$	$h_{4,2,0}$	$h_{3,3,0}$	$h_{2,4,0}$
$x_1 x_2^2$	5544	80568	-77472	798336	-965304	1023336	$h_{4,2,0}$	$h_{3,3,0}$	$h_{2,4,0}$	$h_{1,5,0}$
$x_2^3$	-5916	-77472	88518	-965304	1023336	-1107804	$h_{3,3,0}$	$h_{2,4,0}$	$h_{1,5,0}$	$h_{0,6,0}$

Notice that we do not know the elements in some positions of the matrix.



## Example

In our example the  $4 \times 4$  principal minor is of full rank, so there is no need for re-arranging the matrix. The matrix  $\mathbb{H}_\Lambda^B$  is

$$\mathbb{H}_\Lambda^B = \begin{bmatrix} 38 & -24 & 36 & 1272 \\ -24 & 1272 & -288 & -3456 \\ 36 & -288 & 822 & -7416 \\ 1272 & -3456 & -7416 & 166368 \end{bmatrix}$$

with monomial basis  $B$  equal to  $\{1, x_1, x_2, x_1^2\}$ .

## Example

The shifted matrix  $\mathbb{H}_{x_1 \star \Lambda}^B$  is

$$\mathbb{H}_{x_1 \star \Lambda}^B = \begin{bmatrix} -24 & 1272 & -288 & -3456 \\ 1272 & -3456 & -7416 & 166368 \\ -288 & -7416 & 5544 & -41472 \\ -3456 & 166368 & -41472 & -497664 \end{bmatrix}$$

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We check the commutations relations.

## Example

We solve the generalized eigenvalue/eigenvector problem  $(\mathbb{H}_{X_i \star \Lambda} - \lambda \mathbb{H}_\Lambda)X = 0$  for  $i = 1, 2$ .

## Example

We get the common eigenvectors in the basis  $B = \{1, x_1, x_2, x_1^2\}$

$$\begin{bmatrix} 1 \\ -12 \\ -3 \\ 144 \end{bmatrix}, \begin{bmatrix} 1 \\ 12 \\ -13 \\ 144 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}$$

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Thus, we can deduce the roots and write the following decomposition:

$$f = c_1(x_0 + 2x_1 + 3x_2)^5 + c_2(x_0 - 2x_1 + 3x_2)^5 + c_3(x_0 - 12x_1 - 3x_2)^5 + c_4(x_0 + 12x_1 - 13x_2)^5$$

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It remains to compute  $c_i$ 's. We get that:  $c_1 = 1$ ,  $c_2 = 1$ ,  $c_3 = 1/3$  and  $c_4 = 1/5$ .

## Example

Consider a tensor of dimension three and order 4, that corresponds to the following homogeneous polynomial

$$f = 79 x_0 x_1^3 + 56 x_0^2 x_2^2 + 49 x_1^2 x_2^2 + 4 x_0 x_1 x_2^2 + 57 x_0^3 x_1,$$

the rank of which is 6.



# Example

	1	$x_1$	$x_2$	$x_1^2$	$x_1 x_2$	$x_2^2$	$x_1^3$	$x_1^2 x_2$	$x_1 x_2^2$	$x_2^3$	$x_1^4$	$x_1^3 x_2$	$x_1^2 x_2^2$	$x_1 x_2^3$	$x_2^4$
1	0	$\frac{57}{4}$	0	0	0	$\frac{28}{3}$	$\frac{79}{4}$	0	$\frac{1}{3}$	0	0	0	$\frac{49}{6}$	0	0
$x_1$	$\frac{57}{4}$	0	0	$\frac{79}{4}$	0	$\frac{1}{3}$	0	0	$\frac{49}{6}$	0	$h_{500}$	$h_{410}$	$h_{320}$	$h_{230}$	$h_{140}$
$x_2$	0	0	$\frac{28}{3}$	0	$\frac{1}{3}$	0	0	$\frac{49}{6}$	0	0	$h_{410}$	$h_{320}$	$h_{230}$	$h_{140}$	$h_{050}$
$x_1^2$	0	$\frac{79}{4}$	0	0	0	$\frac{49}{6}$	$h_{500}$	$h_{410}$	$h_{320}$	$h_{230}$	$h_{600}$	$h_{510}$	$h_{420}$	$h_{330}$	$h_{240}$
$x_1 x_2$	0	0	$\frac{1}{3}$	0	$\frac{49}{6}$	0	$h_{410}$	$h_{320}$	$h_{230}$	$h_{140}$	$h_{510}$	$h_{420}$	$h_{330}$	$h_{240}$	$h_{150}$
$x_2^2$	$\frac{28}{3}$	$\frac{1}{3}$	0	$\frac{49}{6}$	0	0	$h_{320}$	$h_{230}$	$h_{140}$	$h_{050}$	$h_{420}$	$h_{330}$	$h_{240}$	$h_{150}$	$h_{060}$
$x_1^3$	$\frac{79}{4}$	0	0	$h_{500}$	$h_{410}$	$h_{320}$	$h_{600}$	$h_{510}$	$h_{420}$	$h_{330}$	$h_{700}$	$h_{610}$	$h_{520}$	$h_{430}$	$h_{340}$
$x_1^2 x_2$	0	0	$\frac{49}{6}$	$h_{410}$	$h_{320}$	$h_{230}$	$h_{510}$	$h_{420}$	$h_{330}$	$h_{240}$	$h_{610}$	$h_{520}$	$h_{430}$	$h_{340}$	$h_{250}$
$x_1 x_2^2$	$\frac{1}{3}$	$\frac{49}{6}$	0	$h_{320}$	$h_{230}$	$h_{140}$	$h_{420}$	$h_{330}$	$h_{240}$	$h_{150}$	$h_{520}$	$h_{430}$	$h_{340}$	$h_{250}$	$h_{160}$
$x_2^3$	0	0	0	$h_{230}$	$h_{140}$	$h_{050}$	$h_{330}$	$h_{240}$	$h_{150}$	$h_{060}$	$h_{430}$	$h_{340}$	$h_{250}$	$h_{160}$	$h_{070}$
$x_1^4$	0	$h_{500}$	$h_{410}$	$h_{600}$	$h_{510}$	$h_{420}$	$h_{700}$	$h_{610}$	$h_{520}$	$h_{430}$	$h_{800}$	$h_{710}$	$h_{620}$	$h_{530}$	$h_{440}$
$x_1^3 x_2$	0	$h_{410}$	$h_{320}$	$h_{510}$	$h_{420}$	$h_{330}$	$h_{610}$	$h_{520}$	$h_{430}$	$h_{340}$	$h_{710}$	$h_{620}$	$h_{530}$	$h_{440}$	$h_{350}$
$x_1^2 x_2^2$	$\frac{49}{6}$	$h_{320}$	$h_{230}$	$h_{420}$	$h_{330}$	$h_{240}$	$h_{520}$	$h_{430}$	$h_{340}$	$h_{250}$	$h_{620}$	$h_{530}$	$h_{440}$	$h_{350}$	$h_{260}$
$x_1 x_2^3$	0	$h_{230}$	$h_{140}$	$h_{330}$	$h_{240}$	$h_{150}$	$h_{430}$	$h_{340}$	$h_{250}$	$h_{160}$	$h_{530}$	$h_{440}$	$h_{350}$	$h_{260}$	$h_{170}$
$x_2^4$	0	$h_{140}$	$h_{050}$	$h_{240}$	$h_{150}$	$h_{060}$	$h_{340}$	$h_{250}$	$h_{160}$	$h_{070}$	$h_{440}$	$h_{350}$	$h_{260}$	$h_{170}$	$h_{080}$

## Example

In our example the  $6 \times 6$  principal minor is of full rank. The matrix  $\mathbb{H}_\Lambda$  is

$$\mathbb{H}_\Lambda = \begin{bmatrix} 0 & \frac{57}{4} & 0 & 0 & 0 & \frac{28}{3} \\ \frac{57}{4} & 0 & 0 & \frac{79}{4} & 0 & \frac{1}{3} \\ 0 & 0 & \frac{28}{3} & 0 & \frac{1}{3} & 0 \\ 0 & \frac{79}{4} & 0 & 0 & 0 & \frac{49}{6} \\ 0 & 0 & \frac{1}{3} & 0 & \frac{49}{6} & 0 \\ \frac{28}{3} & \frac{1}{3} & 0 & \frac{49}{6} & 0 & 0 \end{bmatrix}$$

The columns (and the rows) of the matrix correspond to the monomials  $\{1, x_1, x_2, x_1^2, x_1 x_2, x_2^2\}$ .

## Example

The shifted matrix  $\mathbb{H}_{x_1 \star \Lambda}$  is

$$\mathbb{H}_{x_1 \star \Lambda} = \begin{bmatrix} \frac{57}{4} & 0 & 0 & \frac{79}{4} & 0 & \frac{1}{3} \\ 0 & \frac{79}{4} & 0 & 0 & 0 & \frac{49}{6} \\ 0 & 0 & \frac{1}{3} & 0 & \frac{49}{6} & 0 \\ \frac{79}{4} & 0 & 0 & h_{500} & h_{410} & h_{320} \\ 0 & 0 & \frac{49}{6} & h_{410} & h_{320} & h_{230} \\ \frac{1}{3} & \frac{49}{6} & 0 & h_{320} & h_{230} & h_{140} \end{bmatrix}$$

Since not all the entries of  $\mathbb{H}_{x_1 \star \Lambda}$  are known, we need to compute them in order to proceed further.

## Example

Since we have only **two** variables, there is only **one** matrix equation,

$$M_{x_j} M_{x_j} - M_{x_i} M_{x_i} = H_{\Lambda}^{-1} H_{x_1 * \Lambda} H_{\Lambda}^{-1} H_{x_2 * \Lambda} - H_{\Lambda}^{-1} H_{x_2 * \Lambda} H_{\Lambda}^{-1} H_{x_1 * \Lambda} = \mathbb{O}.$$

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Many of the resulting equations are trivial. After discarding them, we have 6 unknowns  $\{h_{500}, h_{410}, h_{320}, h_{230}, h_{140}, h_{050}\}$  and 15 equations.

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A solution of the system is the following

$$\{h_{500} = 1, h_{410} = 2, h_{320} = 3, h_{230} = 1.5060, h_{140} = 4.960, h_{050} = 0.056\}.$$

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$$\mathbb{M}_{x_j} \mathbb{M}_{x_j} - \mathbb{M}_{x_i} \mathbb{M}_{x_i} = \mathbb{H}_{\Lambda}^{-1} \mathbb{H}_{x_1 \star \Lambda} \mathbb{H}_{\Lambda}^{-1} \mathbb{H}_{x_2 \star \Lambda} - \mathbb{H}_{\Lambda}^{-1} \mathbb{H}_{x_2 \star \Lambda} \mathbb{H}_{\Lambda}^{-1} \mathbb{H}_{x_1 \star \Lambda} = \mathbb{O}.$$

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A solution of the system is the following

$$\{h_{500} = 1, h_{410} = 2, h_{320} = 3, h_{230} = 1.5060, h_{140} = 4.960, h_{050} = 0.056\}.$$

We substitute these values to  $\mathbb{H}_{x_i \star \Lambda}$  and we continue the algorithm as in the previous example.