

# A Numerical Linear Algebra Framework for Solving Problems with Multivariate Polynomials

Kim Batselier

KU Leuven  
Department of Electrical Engineering  
STADIUS Center for Dynamical Systems, Signal Processing, and Data Analytics

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2013

# Outline

- 1 Introduction
- 2 Basis Operations in the Framework
- 3 "Advanced" Operations in the Framework
- 4 Conclusions and Future Work

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## How do multivariate polynomials look like?

Remember from your high school days

- $9x^2 - 5x + 2$
- $x^3 + x^2 - x$

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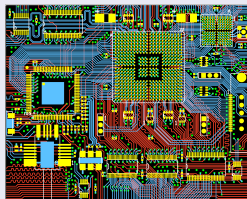
### Now with more than 1 'x'

- $x_1 x_2^2 + x_1 x_3^2 - 1.1 x_1 + 1$
- $-x_1 x_3^3 + 4 x_2 x_3^2 x_4 + 4 x_1 x_3 x_4^2 + 2 x_2 x_4^3 + 4 x_1 x_3 + 4 x_3^2 - 10 x_2 x_4 - 10 x_4^2 + 2$
- $5.22 x_1 x_2^4 + 3.98 x_1^3 - x_2^4 - 3 x_2^2$
- $9.124 x_1^2 x_2 - 2.22 x_1^2$
- $2 x_1 x_2^4 - x_1^3 - 2 x_2^4 + x_1^2$

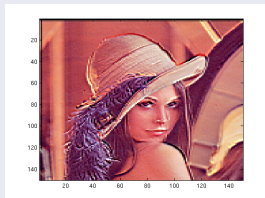
## In which engineering domains do this kind of polynomials appear?



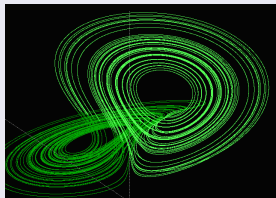
**Computational  
Biology**



**Circuit Design**



**Signal Processing**

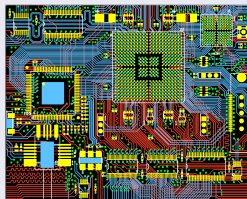


**Nonlinear Dynamical  
Systems**

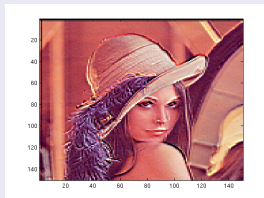
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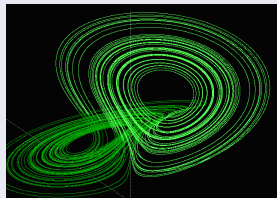
**Computational  
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**Nonlinear Dynamical  
Systems**

**And many others...**

## What needs to be done with these multivariate polynomials?

- Find the solutions,
- Multiply and divide,
- Eliminate variables,
- Compute least common multiples and greatest common divisors,
- ...



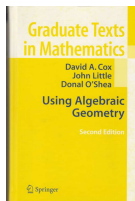
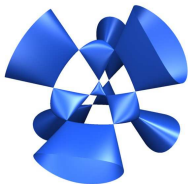
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How are these problems mostly solved these days?

## Algebraic Geometry

- Branch of mathematics



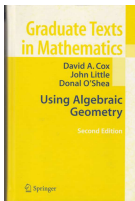
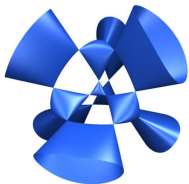
**Wolfgang Gröbner**  
(1899-1980)



**Bruno Buchberger**

## Algebraic Geometry

- Branch of mathematics
- Symbolic operations



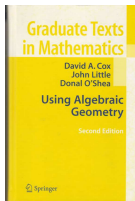
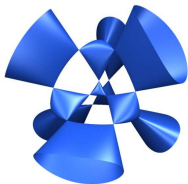
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## Algebraic Geometry

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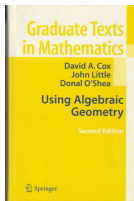
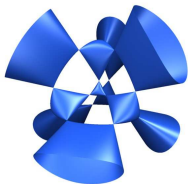
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## Algebraic Geometry

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- Huge body of literature in Algebraic Geometry



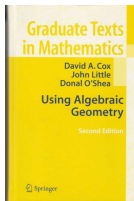
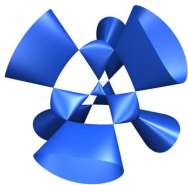
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## Algebraic Geometry

- Branch of mathematics
- Symbolic operations
- Computer algebra software
- Huge body of literature in Algebraic Geometry
- **Produces exact results for exact data!!**



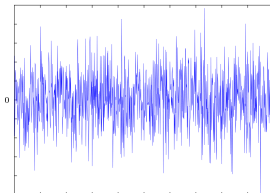
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Engineers do not usually work with exact data

Uncertainties in the measurements  $\Rightarrow$  uncertainties in the coefficients of the multivariate polynomials



## Engineers do not need exact solutions

$$\begin{pmatrix} -85 & -55 & -37 & -35 & 97 & 50 & 79 & 56 & 49 & 63 \\ 57 & -59 & 45 & -8 & -93 & 92 & 43 & -62 & 77 & 66 \\ 54 & -5 & 99 & -61 & -50 & -12 & -18 & 31 & -26 & -62 \\ 1 & -47 & -91 & -47 & -61 & 41 & -58 & -90 & 53 & -1 \\ 94 & 83 & -86 & 23 & -84 & 19 & -50 & 88 & -53 & 85 \\ 49 & 78 & 17 & 72 & -99 & -85 & -86 & 30 & 80 & 72 \\ 66 & -29 & -91 & -53 & -19 & -47 & 68 & -72 & -87 & 79 \\ 43 & -66 & -53 & -61 & -23 & -37 & 31 & -34 & -42 & 88 \\ -76 & -65 & 25 & 28 & -61 & -60 & 9 & 29 & -66 & -32 \\ 78 & 39 & 94 & 68 & -17 & -98 & -36 & 40 & 22 & 5 \end{pmatrix} z = \begin{pmatrix} -88 \\ -43 \\ -73 \\ 25 \\ 4 \\ -59 \\ 62 \\ -55 \\ 25 \\ 9 \end{pmatrix}$$

(from Numerical Polynomial Algebra - H.J. Stetter)



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$$z = \left( \frac{782834491243408476131}{871457446318467875527}, \frac{-248567971271325197781}{871457446318467875527}, \frac{-1141741239586916224104}{871457446318467875527}, \dots \right)^T$$

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$$\tilde{z} = (.8983049, -.2852325, -1.3101515, \dots, -1.6168161)^T$$

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## Language problem

- Algebraic Geometry not in the normal curriculum of most engineers
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## Example: First sentence of the online description of the GROEBNER package of Maple 7

“The GROEBNER package is a collection of routines for doing Groebner basis calculations in skew algebras like Weyl and Ore algebras and in corresponding modules like D-modules” .

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Engineers do speak (numerical) linear algebra!



Richard Feynman

## Seeing things from a Numerical Linear Algebra perspective

- Is it possible to use Numerical Linear Algebra instead?
- New insights/interpretations?
- New methods?



Richard Feynman

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## This thesis:

The development of a Numerical Linear Algebra framework to solve problems with multivariate polynomials.

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## Building blocks of multivariate polynomials?

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Monomials!

$$1, x_1, x_2, x_3, x_1^2, x_1x_2, x_1x_3, x_2^2, x_2x_3, x_3^2, \dots$$

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- ordering
- $\deg(x_1^2) = \deg(x_2x_3) = 2$

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## Example

$$f_1 =$$

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## Example

$$f_1 = 2.76 x_1^2$$

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## Example

$$f_1 = 2.76 x_1^2 - 5.51 x_1 x_3$$

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## Example

$$f_1 = 2.76 x_1^2 - 5.51 x_1 x_3 - 1.12 x_1$$

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## Example

$$f_1 = 2.76 x_1^2 - 5.51 x_1 x_3 - 1.12 x_1 + 1.99$$



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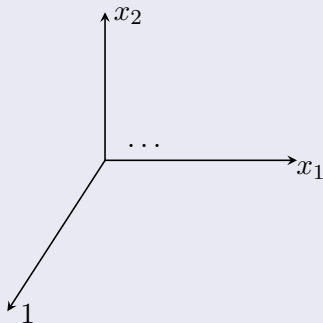
## Example

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$$\text{degree of } f_1 = \deg(f_1) = 2$$

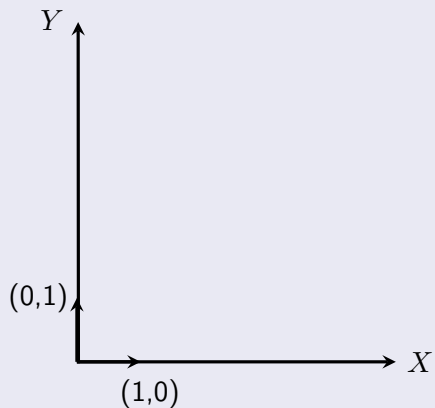
## Vector Representation

Each monomial corresponds with a vector, each orthogonal with respect to all the others:



$C_d^n$ : vector space of all polynomials in  $n$  variables with complex coefficients up to a degree  $d$

## A blast from the past



Each monomial is described by a coefficient vector:

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$$1 \sim ( 1 \ 0 \ 0 \ 0 \ 0 \ \dots )$$

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## Coefficient vector of multivariate polynomial

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$$-5.51 ( 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0 )$$

$$-1.12 ( 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 )$$

$$+1.99 ( 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 )$$

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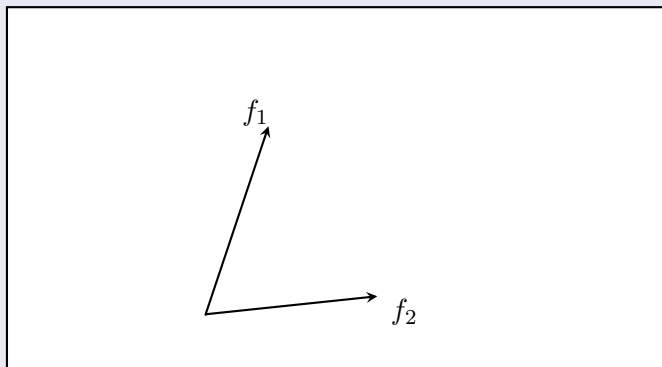
$$-1.12 ( 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 )$$

$$+1.99 ( 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 )$$

$$f_1 \sim ( 1.99 \ -1.12 \ 0 \ 0 \ 2.76 \ 0 \ -5.51 \ 0 \ 0 \ 0 )$$

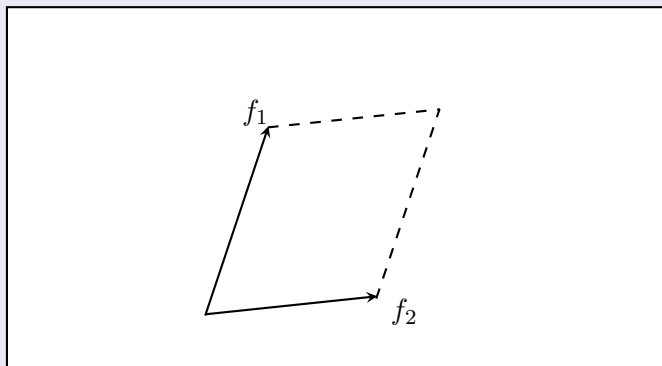
## Addition of Polynomials

Addition of vectors:



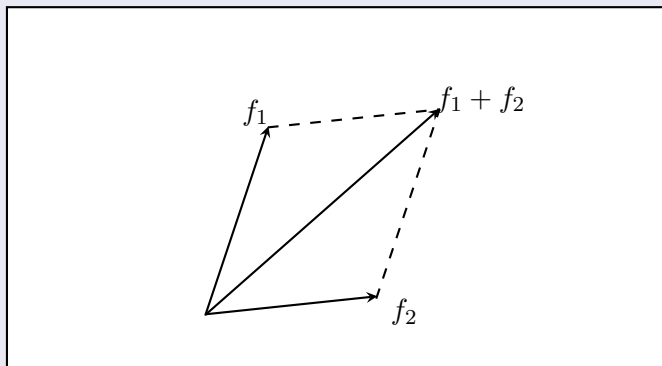
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## Multiplication of 2 multivariate polynomials $h, f \in C_d^n$

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$$f \times h$$

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$$= f \times (h_0 + h_1 x_1 + h_2 x_2 + \dots + h_q x_n^{d_h})$$

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$$\sim (h_0 \quad h_1 \quad h_2 \quad \dots \quad h_q) \begin{pmatrix} f \\ x_1 f \\ x_2 f \\ \vdots \\ x_n^{d_h} f \end{pmatrix}$$

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$$\sim h M_f$$

## Multiplication Example

$$f = x_1x_2 - x_2 \text{ and } h = x_1^2 + 2x_2 - 9.$$

$$h M_f = \begin{pmatrix} -9 & 0 & 2 & 1 & 0 & 0 \end{pmatrix} \begin{pmatrix} f \\ x_1f \\ x_2f \\ x_1^2f \\ x_1x_2f \\ x_2^2f \end{pmatrix}.$$

## Multiplication Example

$$M_f =$$

$$\begin{array}{c}
 f \\
 x_1 f \\
 x_2 f \\
 x_1^2 f \\
 x_1 x_2 f \\
 x_2^2 f
 \end{array}
 \begin{pmatrix}
 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_2^3 & x_1^4 & x_1^3 x_2 & x_1^2 x_2^2 & x_1 x_2^3 & x_2^4 \\
 0 & 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
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 \end{pmatrix}$$



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$$hM_f =$$

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 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_2^3 & x_1^4 & x_1^3 x_2 & x_1^2 x_2^2 & x_1 x_2^3 & x_2^4 \\
 0 & 0 & 9 & 0 & -9 & -2 & 0 & -1 & 2 & 0 & 0 & 1 & 0 & 0 & 0
 \end{pmatrix}$$

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 \end{array}
 \begin{pmatrix}
 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_2^3 & x_1^4 & x_1^3 x_2 & x_1^2 x_2^2 & x_1 x_2^3 & x_2^4 \\
 0 & 0 & -1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1 & 0
 \end{pmatrix}$$

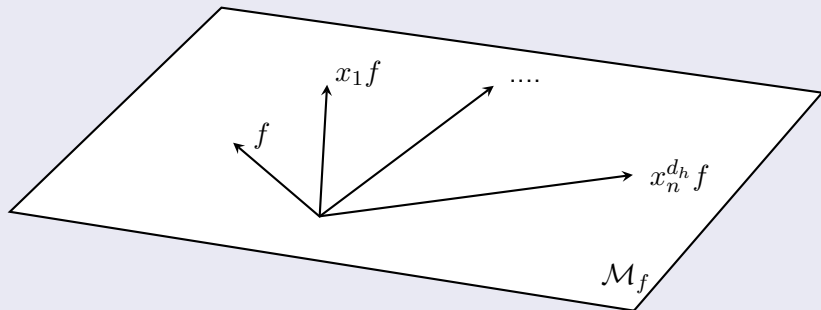
$$hM_f =$$

$$\begin{pmatrix}
 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_2^3 & x_1^4 & x_1^3 x_2 & x_1^2 x_2^2 & x_1 x_2^3 & x_2^4 \\
 0 & 0 & 9 & 0 & -9 & -2 & 0 & -1 & 2 & 0 & 0 & 1 & 0 & 0 & 0
 \end{pmatrix}$$

$$\sim 9x_2 - 9x_1x_2 - 2x_2^2 - x_1^2x_2 + 2x_1x_2^2 + x_1^3x_2$$

## Multiplication of Polynomials

Every possible multiplication of  $f$  lies in a vector space  $\mathcal{M}_f$  spanned by  $f, x_1 f, x_2 f, \dots$



## Definition multivariate polynomials

Fix any monomial order  $>$  on  $C_d^n$  and let  $F = (f_1, \dots, f_s)$  be a  $s$ -tuple of polynomials in  $C_d^n$ . Then every  $p \in C_d^n$  can be written as

$$p = h_1 f_1 + \dots + h_s f_s + r$$

where  $h_i, r \in C_d^n$ . For each  $i$ ,  $h_i f_i = 0$  or  $\text{LM}(p) \geq \text{LM}(h_i f_i)$ , and either  $r = 0$ , or  $r$  is a linear combination of monomials, none of which is divisible by any of  $\text{LM}(f_1), \dots, \text{LM}(f_s)$ .

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## Differences with division of numbers

- Remainder  $r$  depends on the way we order monomials
- Dividends  $h_1, \dots, h_s$  and remainder  $r$  depend on order of divisors  $f_1, \dots, f_s$

## Describing the quotient

$$p = h_1 f_1 + \dots + h_s f_s + r$$

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## Describing the quotient

$$p = h_1 f_1 + \dots + h_s f_s + r$$

$$(h_{k0} \quad h_{k1} \quad h_{k2} \quad \dots \quad h_{kw}) \begin{pmatrix} f_k \\ x_1 f_k \\ x_2 f_k \\ \vdots \\ x_n^{d_k} f_k \end{pmatrix}$$

## Describing the quotient

$$p = h_1 f_1 + \dots + h_s f_s + r$$

$$(h_{s0} \quad h_{s1} \quad h_{s2} \quad \dots \quad h_{sv}) \begin{pmatrix} f_s \\ x_1 f_s \\ x_2 f_s \\ \vdots \\ x_n^{d_s} f_s \end{pmatrix}$$

## Describing the quotient

$$p = h_1 f_1 + \dots + h_s f_s + r$$

$$(h_{10} \quad h_{11} \quad h_{12} \quad \dots \quad h_{1q} \quad h_{20} \quad h_{21} \quad \dots \quad h_{sv})$$

$$\begin{pmatrix} f_1 \\ x_1 f_1 \\ x_2 f_1 \\ \vdots \\ x_n^{d_1} f_1 \\ f_2 \\ x_1 f_2 \\ \vdots \\ x_n^{d_s} f_s \end{pmatrix}$$

## Divisor Matrix $D$

Given a set of polynomials  $f_1, \dots, f_s \in C_d^n$ , each of degree  $d_i$  ( $i = 1 \dots s$ ) and a polynomial  $p \in C_d^n$  of degree  $d$  then the divisor matrix  $D$  is given by

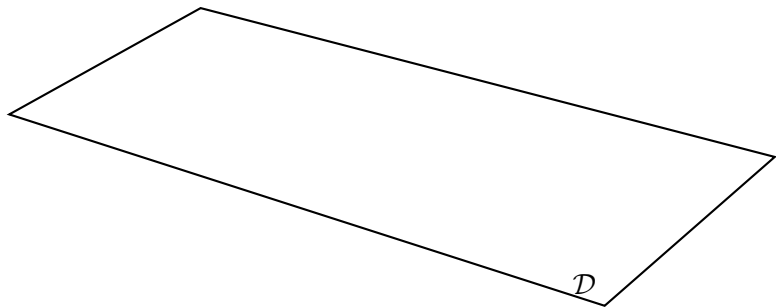
$$D = \begin{pmatrix} f_1 \\ x_1 f_1 \\ x_2 f_1 \\ \vdots \\ x_n^{d_1} f_1 \\ f_2 \\ x_1 f_2 \\ \vdots \\ x_n^{d_s} f_s \end{pmatrix}$$

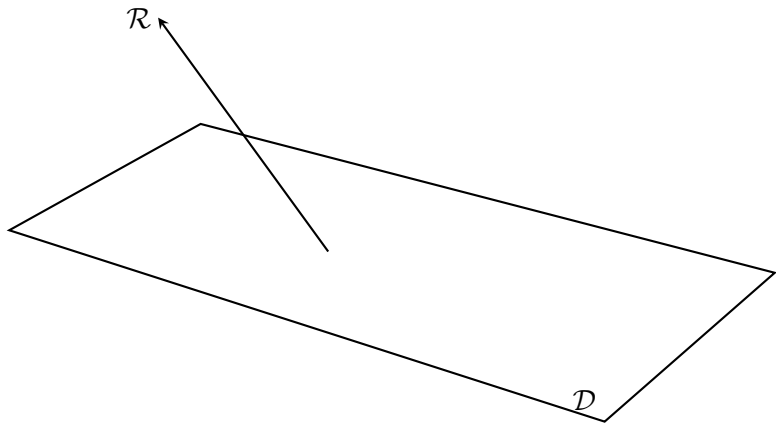
where each polynomial  $f_i$  is multiplied with all monomials  $x^{\alpha_i}$  from degree 0 up to degree  $k_i = \deg(p) - \deg(f_i)$  such that  $x^{\alpha_i} \text{LM}(f_i) \leq \text{LM}(p)$ .

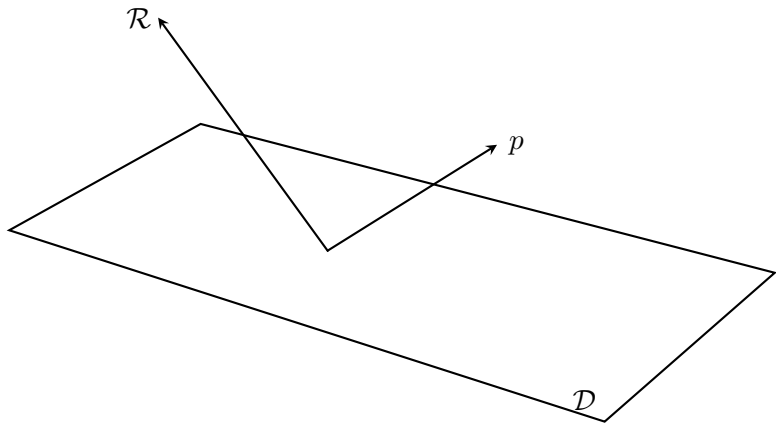
## Example Divisor Matrix

To divide  $p = 4 + 5x_1 - 3x_2 - 9x_1^2 + 7x_1x_2$  by  $f_1 = -2 + x_1 + x_2$ ,  
 $f_2 = 3 - x_1$ :

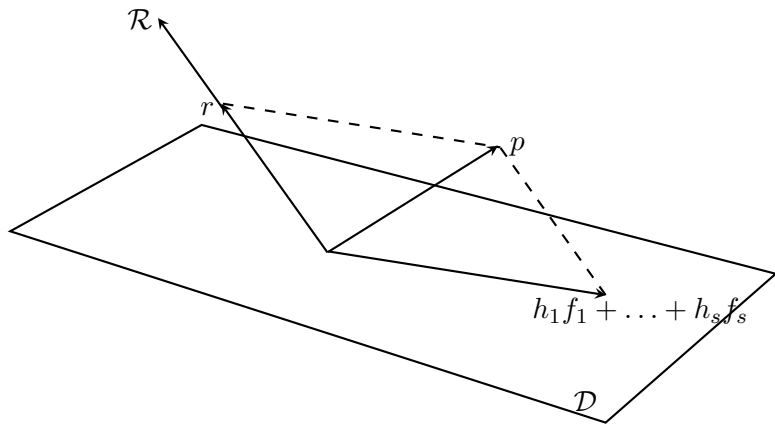
$$D = \begin{array}{l} \\ f_1 \\ x_1 f_1 \\ f_2 \\ x_1 f_2 \\ x_2 f_2 \end{array} \begin{pmatrix} 1 & x_1 & x_2 & x_1^2 & x_1 x_2 \\ -2 & 1 & 1 & 0 & 0 \\ 0 & -2 & 0 & 1 & 1 \\ 3 & -1 & 0 & 0 & 0 \\ 0 & 3 & 0 & -1 & 0 \\ 0 & 0 & 3 & 0 & -1 \end{pmatrix}$$











# Outline

- 1 Introduction
- 2 Basis Operations in the Framework
- 3 "Advanced" Operations in the Framework**
- 4 Conclusions and Future Work

## "Advanced" operations on polynomials

- Eliminate variables
- Compute a least common multiple of 2 multivariate polynomials
- Compute a greatest common divisor of 2 multivariate polynomials

One More Key Player:

Macaulay matrix

## Macaulay Matrix

Given a set of multivariate polynomials  $f_1, \dots, f_s$ , each of degree  $d_i (i = 1 \dots s)$  then the Macaulay matrix of degree  $d$  is given by

$$M(d) = \begin{pmatrix} f_1 \\ x_1 f_1 \\ \vdots \\ x_n^{d-d_1} f_1 \\ f_2 \\ x_1 f_2 \\ \vdots \\ x_n^{d-d_s} f_s \end{pmatrix}$$

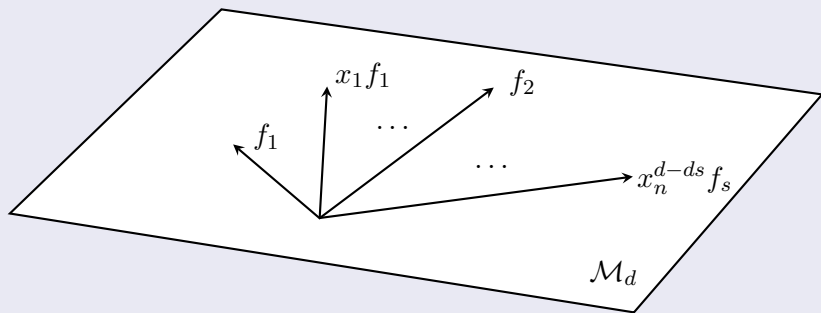
where each polynomial  $f_i$  is multiplied with all monomials up to degree  $d - d_i$  for all  $i = 1 \dots s$ .

## Row space of the Macaulay matrix

$$\mathcal{M}_d = \{h_1 f_1 + h_2 f_2 + \dots + h_s f_s \mid \text{for all possible } h_1, h_2, \dots, h_s \\ \text{with degrees } d - d_1, d - d_2, \dots, d - d_s \text{ respectively}\}$$

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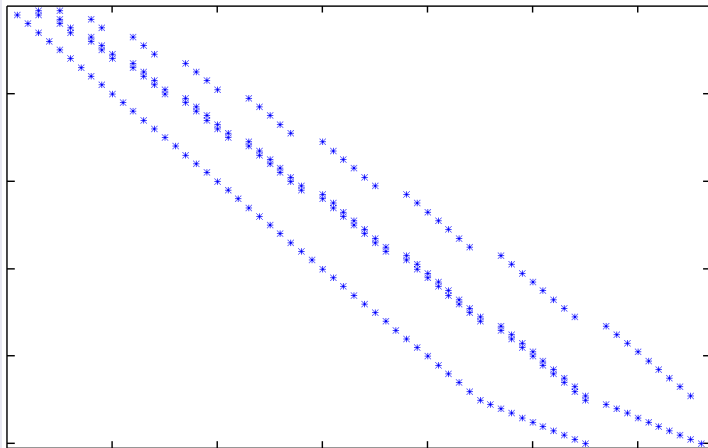


For the following polynomial system:

$$\begin{cases} f_1 : & x_1 x_2 - 2x_2 & = & 0 \\ f_2 : & & x_2 - 3 & = & 0 \end{cases}$$

the Macaulay matrix of degree 3 is

$$M(3) = \begin{matrix} & 1 & x_1 & x_2 & x_1^2 & x_1 x_2 & x_2^2 & x_1^3 & x_1^2 x_2 & x_1 x_2^2 & x_2^3 \\ \begin{matrix} f_1 \\ x_1 f_1 \\ x_2 f_1 \\ f_2 \\ x_1 f_2 \\ x_2 f_2 \\ x_1^2 f_2 \\ x_1 x_2 f_2 \\ x_2^2 f_2 \end{matrix} & \begin{pmatrix} 0 & 0 & -2 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -2 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -2 & 0 & 0 & 0 & 1 & 0 \\ -3 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & -3 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & -3 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -3 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & -3 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -3 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \end{matrix}$$

Sparsity pattern  $M(10)$ 



## Elimination Problem

Given a set of multivariate polynomials  $f_1, \dots, f_s$  and  $x_e \subsetneq \{x_1, \dots, x_n\}$ . Find a polynomial  $g = h_1 f_1 + \dots + h_s f_s$  that does not contain any of the  $x_e$  variables.

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## Example

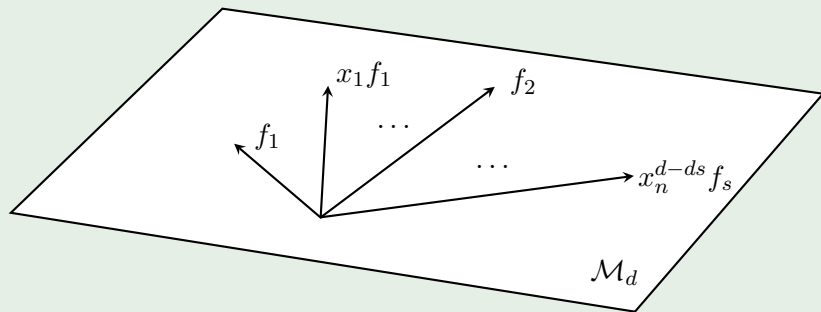
From the following polynomial system in 3 variables  $x_1, x_2, x_3$ :

$$\begin{cases} f_1 &= x_1^2 + x_2 + x_3 - 1, \\ f_2 &= x_1 + x_2^2 + x_3 - 1, \\ f_3 &= x_1 + x_2 + x_3^2 - 1, \end{cases}$$

we want to find a  $g = h_1 f_1 + h_2 f_2 + h_3 f_3$  only in  $x_3$ .

## Example

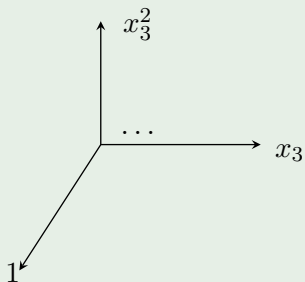
Since  $g = h_1 f_1 + h_2 f_2 + h_3 f_3$ , it lies in



for a certain degree  $d$ .

## Example

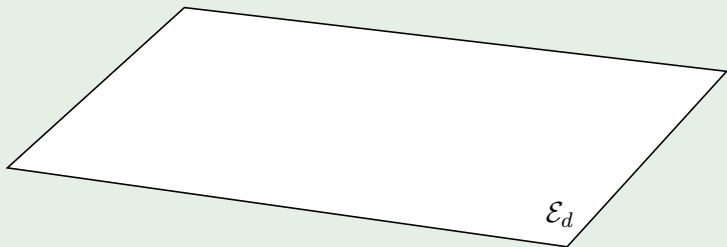
Also, since  $g$  only contains the variables  $x_3$ , it is built up from the monomial basis



up to a certain degree  $d$ .

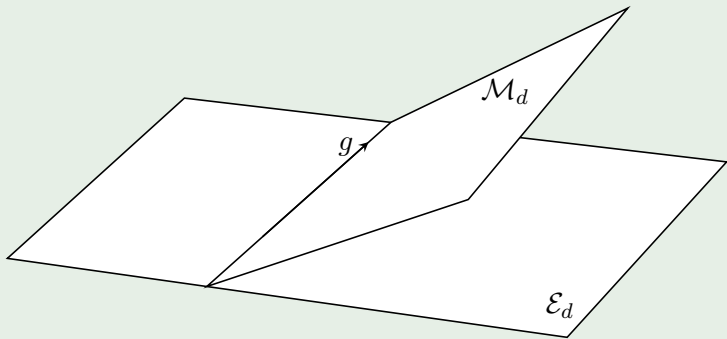
## Example

We will call this vector space that is spanned by the variables  $x_3$   
 $\mathcal{E}_d$ :



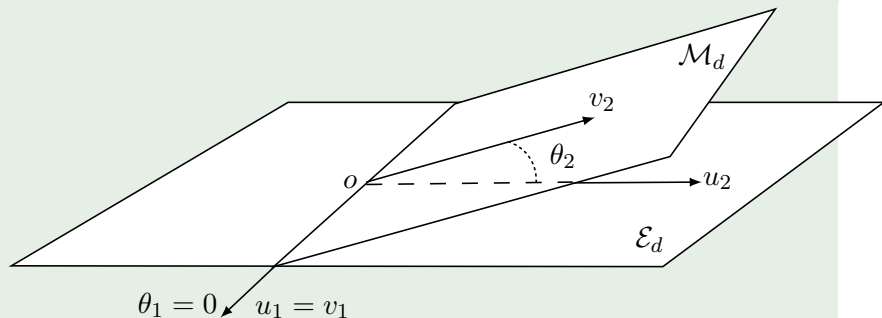
## Example

$g \in \mathcal{M}_d$  and  $g \in \mathcal{E}_d$ ; hence  $g$  lies in the intersection  $\mathcal{M}_d \cap \mathcal{E}_d$ :



for some particular degree  $d$ .

## Finding the intersection



## Example

We revisit

$$\begin{cases} x_1^2 + x_2 + x_3 = 1, \\ x_1 + x_2^2 + x_3 = 1, \\ x_1 + x_2 + x_3^2 = 1. \end{cases}$$

- we eliminate both  $x_1$  and  $x_2$ 
  - $d = 6$ ,
  - $g(x_3) = x_3^2 - 4x_3^3 + 4x_3^4 - x_3^6$ .
- we eliminate  $x_2$ :
  - $d = 2$ ,
  - $g(x_1, x_3) = x_1 - x_3 - x_1^2 + x_3^2$ .



## Least Common Multiple

A multivariate polynomial  $l$  is called a least common multiple (LCM) of 2 multivariate polynomials  $f_1, f_2$  if

- 1  $f_1$  divides  $l$  and  $f_2$  divides  $l$ .
- 2  $l$  divides any polynomial which both  $f_1$  and  $f_2$  divide.

 $f_1$  $f_2$

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 $f_1$  $f_2$  $l = \text{LCM}(f_1, f_2)$

## Finding the LCM

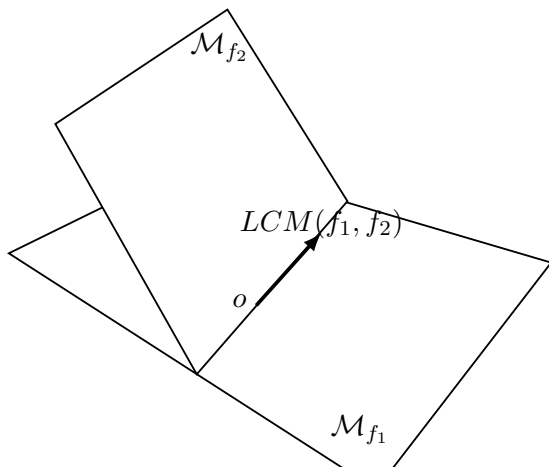
The LCM  $l$  of  $f_1$  and  $f_2$  satisfies:

$$\text{LCM}(f_1, f_2) \triangleq l = f_1 h_1 = f_2 h_2$$

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 $f_1$  $f_2$  $g = \text{GCD}(f_1, f_2)$

## Finding the GCD

Remember that

$$\text{LCM}(f_1, f_2) \triangleq l = f_1 h_1 = f_2 h_2.$$

We also have that

$$f_1 f_2 = l g,$$

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Answer:

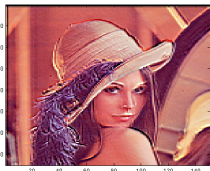
$$g = \frac{f_1 f_2}{l} = \frac{f_1}{h_2} = \frac{f_2}{h_1}.$$



## Blind Image Deconvolution

- $F_1(z_1, z_2) = I(z_1, z_2) D_1(z_1, z_2) + N_1(z_1, z_2)$
- $F_2(z_1, z_2) = I(z_1, z_2) D_2(z_1, z_2) + N_2(z_1, z_2)$
- $I(z_1, z_2) = \tau\text{-GCD}(F_1, F_2)$

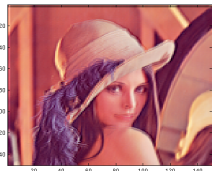
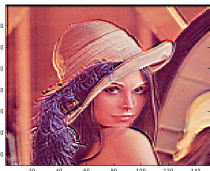


$$F_1(z_1, z_2)$$


$$F_2(z_1, z_2)$$

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 $F_1(z_1, z_2)$ 

 $F_2(z_1, z_2)$ 

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- Counting total number of affine solutions of  $f_1, \dots, f_s$
- Solving the ideal membership problem



# Outline

- 1 Introduction
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## Conclusions

- Numerical Linear Algebra Framework
- Addition, Multiplication
- Polynomial Division and oblique projections
- Elimination and intersection of vector spaces
- LCM and GCD's
- syzygy analysis, counting affine solutions, removing multiplicities of solutions, . . .

## Future Research/Work

- Exploit sparsity + structure matrices
- Numerical Analysis:
  - Polynomial division
  - Intersection of vector spaces
  - Numerical rank
- Open problems:
  - Modelling higher dimensional solution sets
  - Full understanding of roots at infinity
  - ...

